



Tokyo University of Marine Science and Technology

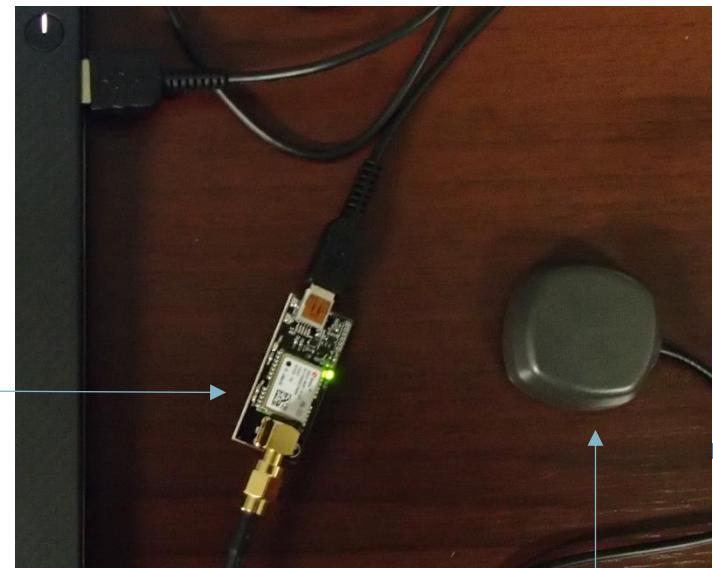
Laboratory of Satellite Navigation Engineering



# How to use Receiver/Antenna Test Package



uBlox receiver

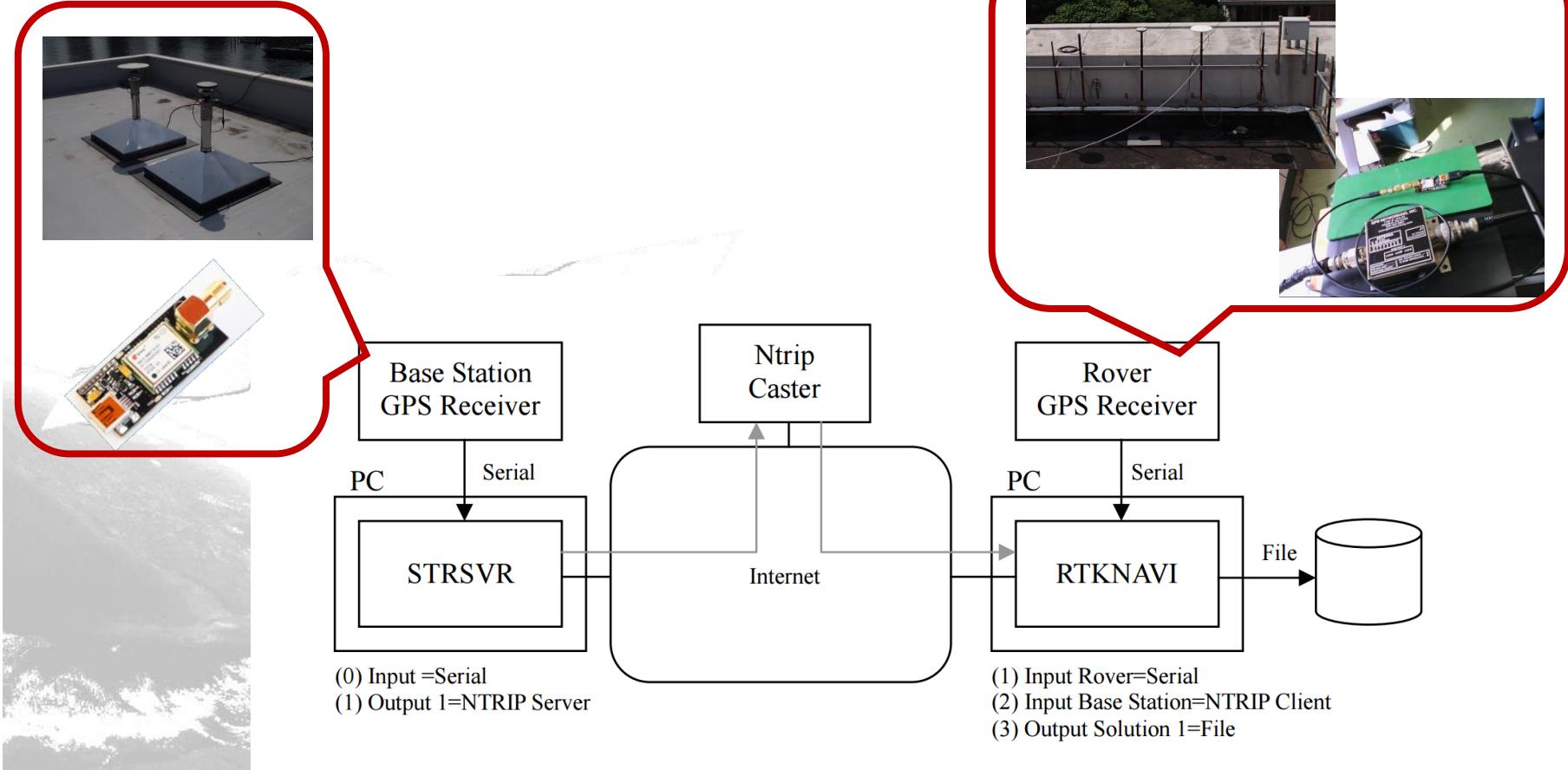


antenna

# Use Ublox as the reference station



- Reference station uploads raw data
- Ntrip server can distribute the data



# Download RTKLIB

The screenshot shows the official RTKLIB website at [www.rtklib.com](http://www.rtklib.com). The main content area displays a table of releases from version 0.2.0 to 2.4.3, with a red box highlighting the first few rows. Below the table, a note says: "Please refer the [support information](#) to get the latest patches. RTKLIB 2.4.3 betas are available at GitHub. ([RTKLIB – branch rtklib\\_2.4.3](#))".

Version	Date	Binary AP Package for Windows	Full Package with Source Programs
0.2.0	2006/12/16	–	<a href="#">rtklib_0.2.0.zip</a> (2.8MB)
1.0.0	2007/01/25	–	<a href="#">rtklib_1.0.0.zip</a> (10.5MB)
1.1.0	2007/03/20	–	<a href="#">rtklib_1.1.0.zip</a> (6.2MB)
2.1.0	2008/07/15	–	<a href="#">rtklib_2.1.0.zip</a> (22.9MB)
2.2.0	2009/01/31	<a href="#">rtklib_2.2.0.bin.zip</a> (10.7MB)	<a href="#">rtklib_2.2.0.zip</a> (23.4MB)
2.2.1	2009/05/17	<a href="#">rtklib_2.2.1.bin.zip</a> (15.3MB)	<a href="#">rtklib_2.2.1.zip</a> (30.6MB)
2.2.2	2009/09/07	<a href="#">rtklib_2.2.2.bin.zip</a> (21.4MB)	<a href="#">rtklib_2.2.2.zip</a> (33.8MB)
2.3.0	2009/12/17	<a href="#">rtklib_2.3.0.bin.zip</a> (26.7MB)	<a href="#">rtklib_2.3.0.zip</a> (35.8MB)
2.4.0	2010/08/08	<a href="#">rtklib_2.4.0.bin.zip</a> (17.4MB)	<a href="#">rtklib_2.4.0.zip</a> (26.5MB)
2.4.1	2011/06/11	<a href="#">rtklib_2.4.1.bin.zip</a> (16.5MB)	<a href="#">rtklib_2.4.1.zip</a> (26.4MB)
2.4.2	2013/04/29	<a href="#">rtklib_2.4.2.bin.zip</a> (30.4MB)	<a href="#">rtklib_2.4.2.zip</a> (55.2MB)
2.4.3	2015/03/31	<a href="#">rtklib_2.4.3.bin.zip</a> (?? MB)	<a href="#">rtklib_2.4.3.zip</a> (?? MB)

[Open Repository in GitHub.](#)

[Tutorial and Demonstration](#)

[GNSS-SDRLIB: Open Source GNSS Software Defined Radio Library](#) (SDR working with RTKLIB)

[Google play: RTKGPS+](#) (Android frontend of RTKLIB)

[Overview](#)

RTKLIB is an open source program package for standard and precise positioning with GNSS (global navigation satellite system). RTKLIB consists of a portable program library and several APs (application programs) utilizing the library. The features of RTKLIB are:

(1) It supports standard and precise positioning algorithms with:

The screenshot shows the RTKLIB repository on GitHub at <https://github.com/tomojitakasu/RTKLIB>. The repository has 128 stars and 262 forks. A red box highlights the "Clone or download" button, which is labeled "Download ZIP".

Personal Open source Business Explore Pricing Blog Support This repository Search Sign in Sign up

tomojitakasu / RTKLIB

74 commits 2 branches 0 releases 1 contributor

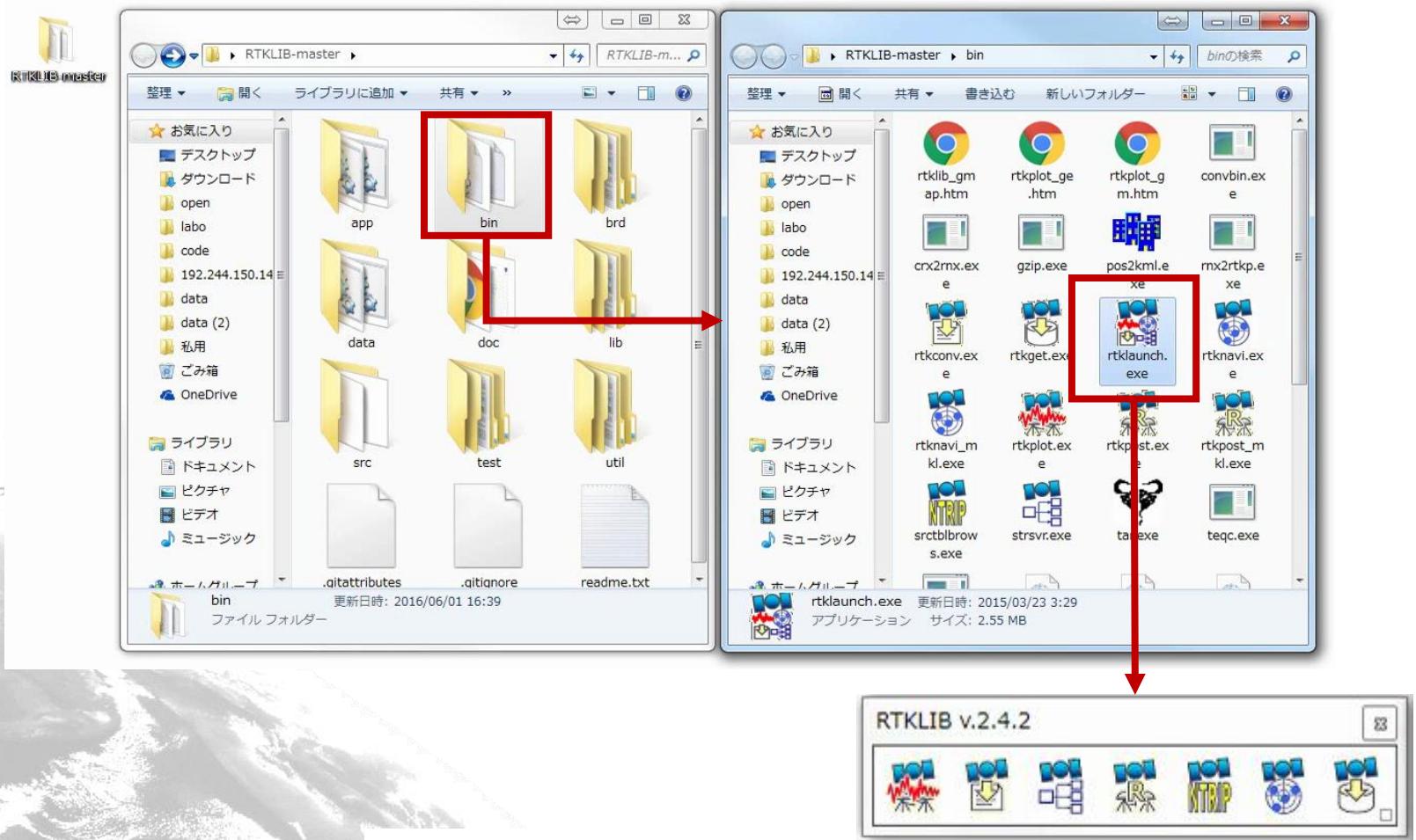
Branch: [rtklib\\_2.4.3](#) New pull request Find file Clone or download

This branch is 74 commits ahead, 39 commits behind master.

tomojitakasu rtklib 2.4.3 b10

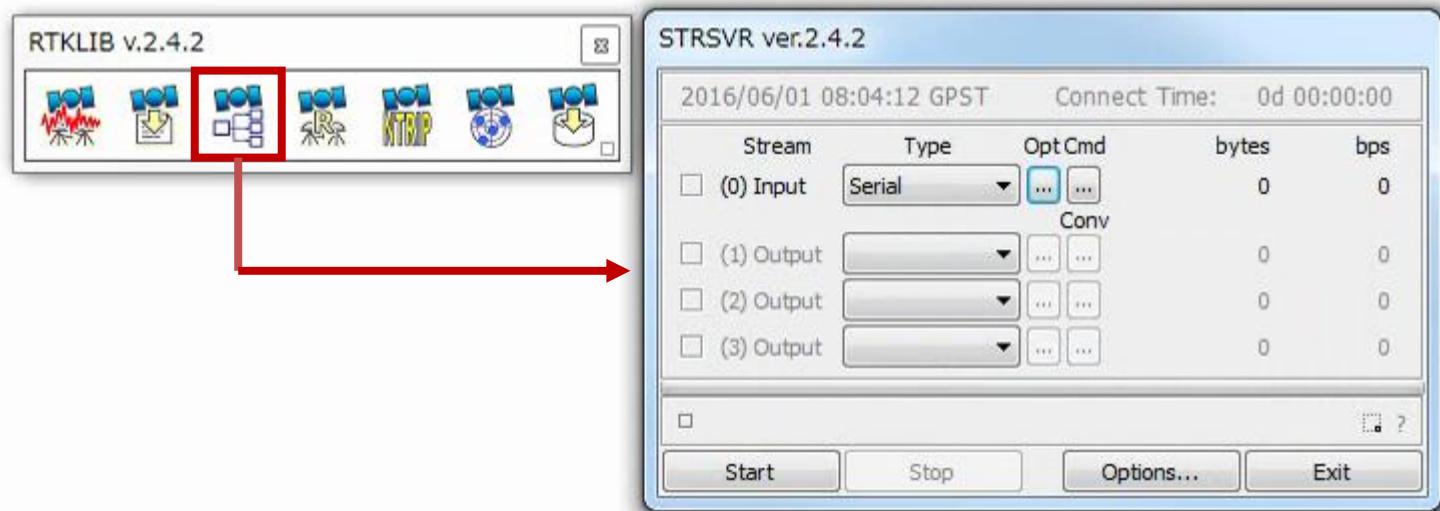
app	rtklib 2.4.3 b10	3 years ago
bin	rtklib 2.4.3 b10	7 days ago
brd	RTKLIB 2.4.2	3 years ago
data	rtklib 2.4.3 b10	3 years ago
doc	RTKLIB 2.4.2	3 years ago
lib	RTKLIB 2.4.2	3 years ago
src	rtklib 2.4.3 b10	7 days ago
test	RTKLIB 2.4.2	3 years ago
util	rtklib 2.4.2 p9	2 years ago
gitattributes	RTKLIB 2.4.2	3 years ago
gitignore	rtklib 2.4.2 p3	3 years ago
readme.txt	rtklib 2.4.3 b10	7 days ago

# Start RTKLIB



# Start STRSVR

- Click the icon that is the third from the left
- STRSVR is the application for the data streaming server
  - We need to select input and output settings
  - Three output files can be selected for each input file



# STRSVR : Setting input and output

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- Select input data source

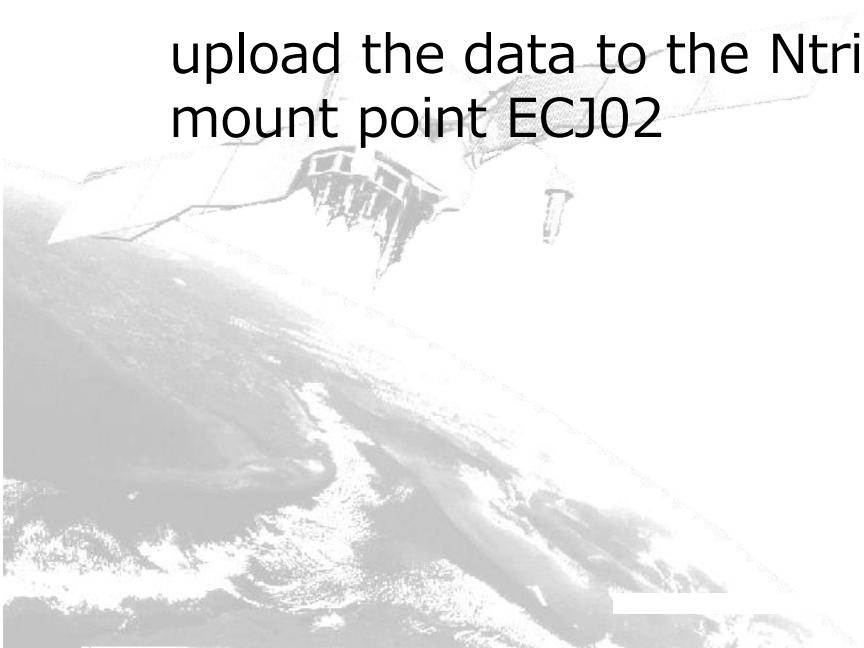
At this time

USB serial port from u-blox receiver: port ##, bitrate:115200

- Select the output data destination

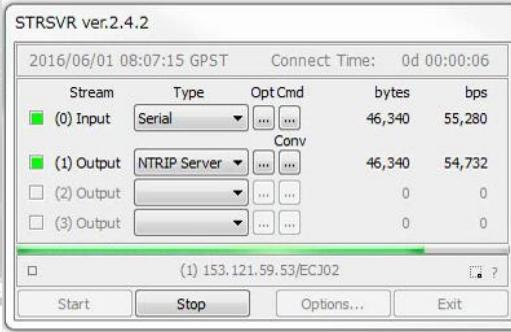
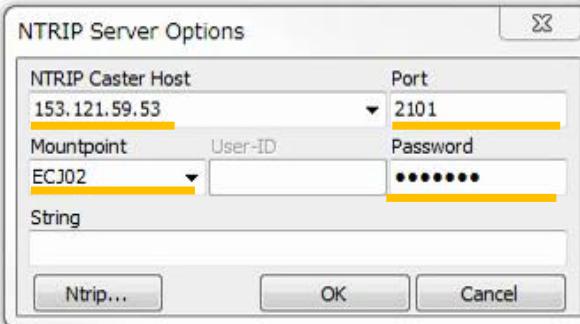
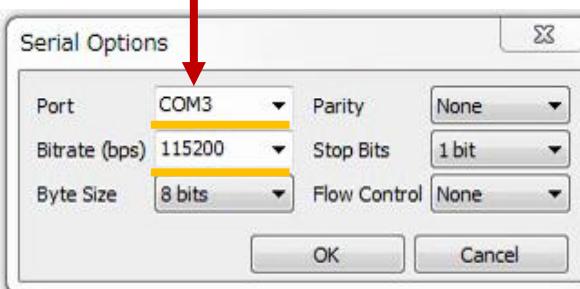
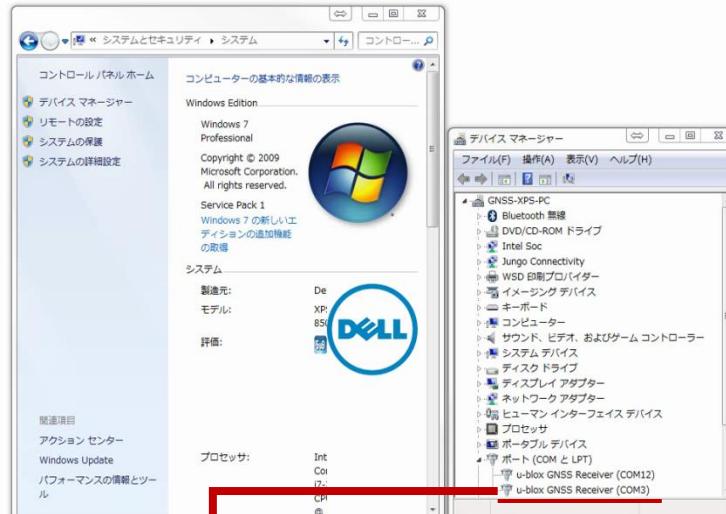
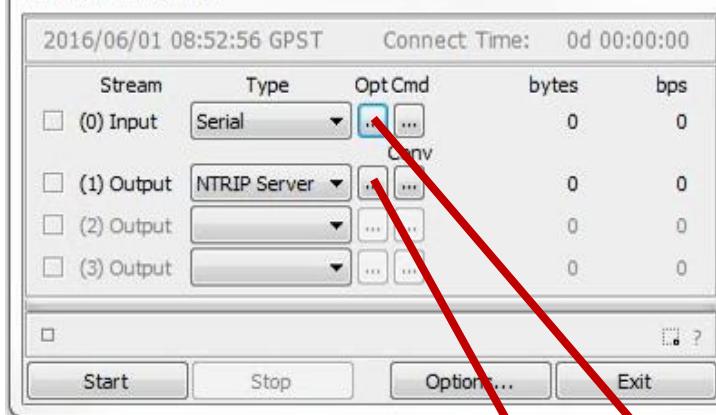
- upload the data to the Ntrip caster prepared in advance within the Ntrip server
  - At this time

upload the data to the Ntrip caster in the Sakura server as mount point ECJ02



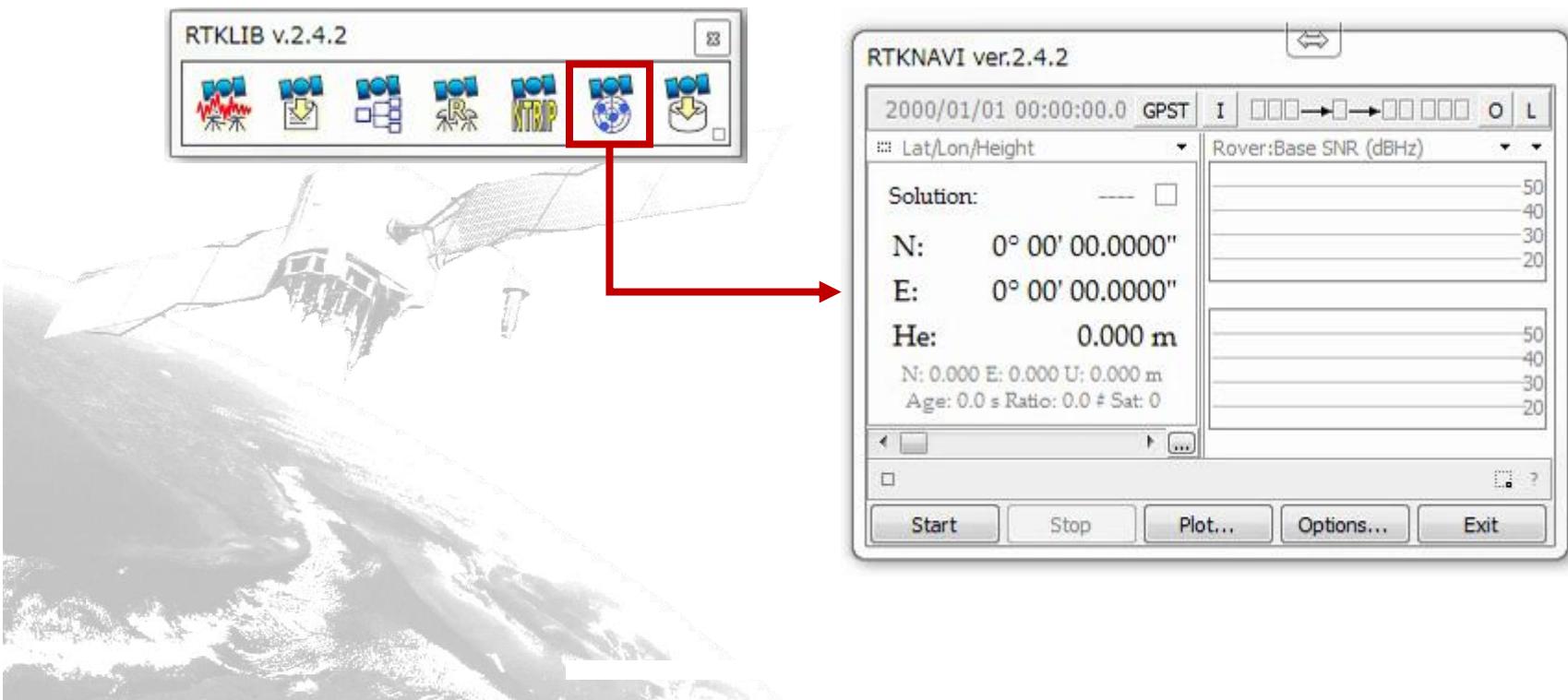
# STRSVR : Setting input and output

STRSVR ver.2.4.2



# Start STRNAVI

- Click the icon that is the second from the right
- STRNAVI is an application for real-time analysis
- It can access logged data

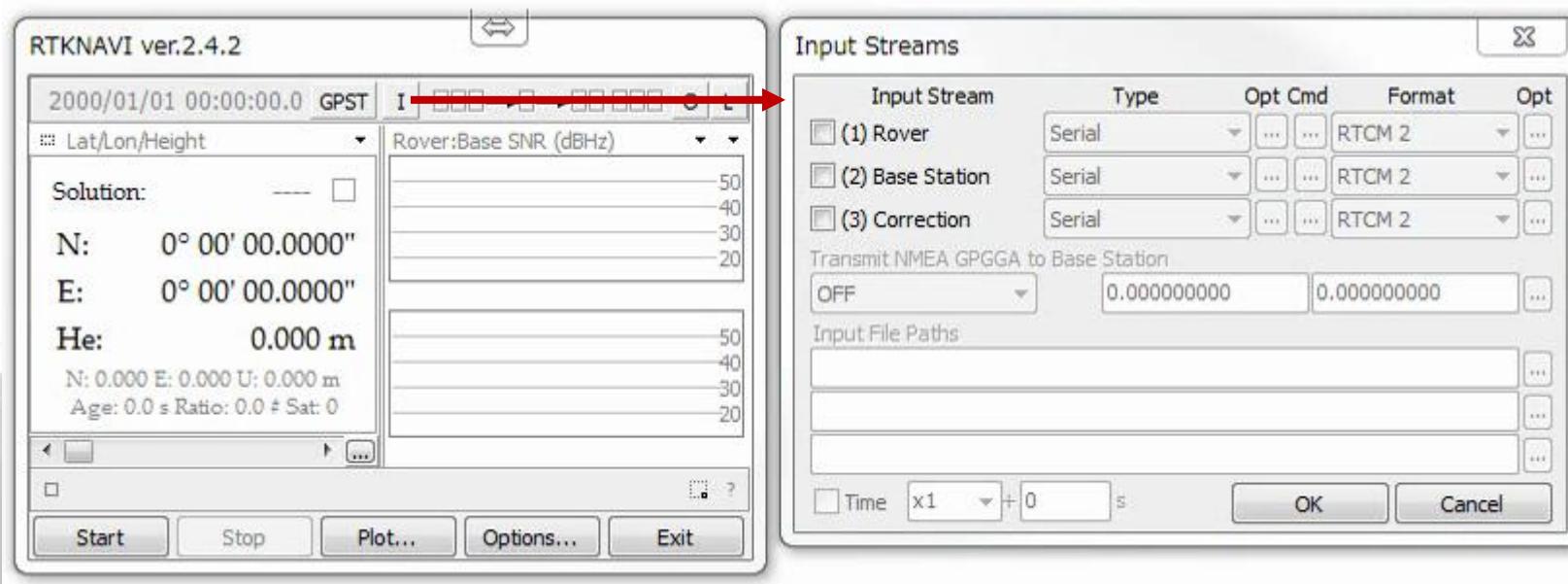


# STRNAVI : Setting input

- Select input data source

Select format to match the input data source

At this time, Base: ECJ02, rover: Serial

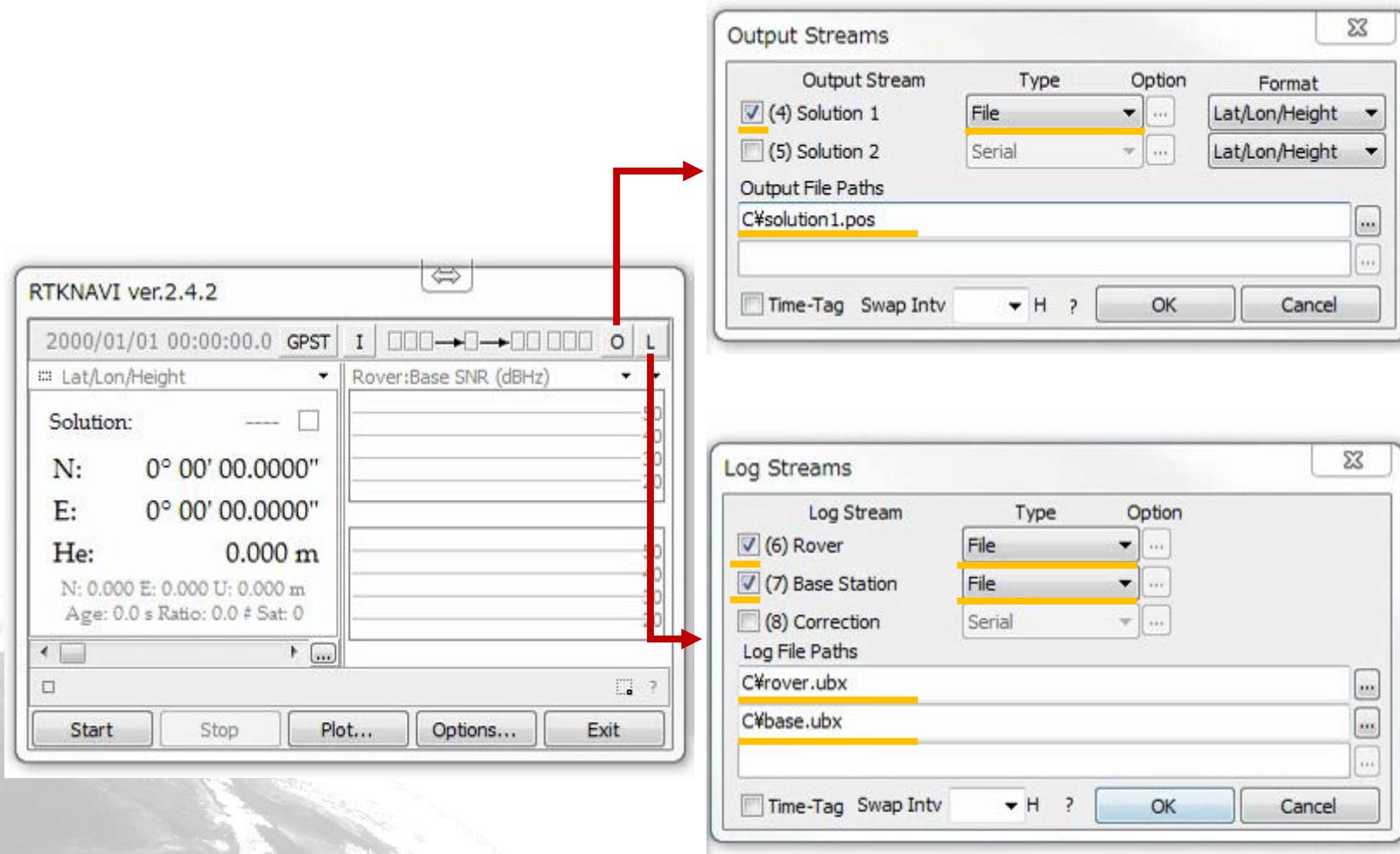


# RTKNAVI : Setting input

The image shows three dialog boxes from the RTKNAVI software interface:

- Input Streams**: A main configuration window with a table of input streams. Stream (1) Rover is selected. Stream (2) Base Station is set to NTRIP Client. Stream (3) Correction is set to Serial. A red bracket on the right side of the table points to the "Serial Options" dialog.
- Serial Options**: A configuration dialog for serial port settings. It includes fields for Port (COM12), Bitrate (bps) (115200), Byte Size (8 bits), Parity (None), Stop Bits (1 bit), and Flow Control (None). A red arrow points from the "Serial" dropdown in the Input Streams dialog to this window.
- NTRIP Client Options**: A configuration dialog for NTRIP client settings. It includes fields for NTRIP Caster Host (153.121.59.53), Port (2101), Mountpoint (ECJ02), User-ID (gspase), and Password (\*\*\*\*\*). A red bracket on the right side of the window points to the "NTRIP..." button.

# RTKNAVI : Setting output



# RTKNAVI : Setting options

The diagram illustrates the RTKNAVI software interface and its configuration options. A red bracket on the left points from the main window to the 'Options' dialog, which is highlighted in red. Three green arrows point from the 'Options' dialog to three separate windows below, each showing different configuration settings.

**Main Window (RTKNAVI ver.2.4.2):**

- Lat/Lon/Height: N: 0° 00' 00.0000", E: 0° 00' 00.0000", He: 0.000 m, N: 0.000 E: 0.000 U: 0.000 m, Age: 0.0 s Ratio: 0.0 Sat: 0
- Rover/Base SNR (dBHz): 50, 40, 30, 20
- Buttons: Start, Stop, Plot..., Options..., Exit

**Options Dialog (highlighted in red):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Positioning Mode: Single	Frequencies / Filter Type: L1+L2 / Forward	Elevation Mask (?) / SNR Mask (dBHz): 15	Rec Dynamics / Earth Tides Correction: OFF / OFF	Ionosphere Correction: Broadcast	Troposphere Correction: Saastamoisen	Satellite Ephemeris/Clock: Broadcast
<input type="checkbox"/> Sat PCV <input type="checkbox"/> Rec PCV <input type="checkbox"/> Ph-Windup <input type="checkbox"/> Reject Ed <input type="checkbox"/> RAIM FDE <input checked="" type="checkbox"/> GPS <input type="checkbox"/> GLO <input type="checkbox"/> Galileo <input type="checkbox"/> QZSS <input type="checkbox"/> SBAS <input type="checkbox"/> BeiDou						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

**Options Dialog (highlighted in red):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Integer Ambiguity Res (GPS/GLO/BDS): Cont	Min Ratio to Fix Ambiguity: 3.0	Min Confidence / Max FCB to Fix Amb: 0.9999	Min Lock / Elevation (?) to Fix Amb: 0	Min Fix / Elevation (?) to Hold Amb: 10	Outage to Reset Amb / Slip Thres (m): 5	Max Age of Diff (s) / Sync Solution: 30.0
<input type="checkbox"/> Baseline Length Constraint (m)						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

**Options Dialog (highlighted in red):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Rover	Lat/Lon/Height (deg/m): -90.000000000	Delta-E/N/U (m): -6378137.0000	Antenna Type (*: Auto)	Base Station	Lat/Lon/Height (deg/m): -90.000000000	Delta-E/N/U (m): -6378137.0000
<input type="checkbox"/> Antenna Type (*: Auto)						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

**Options Dialog (highlighted in green):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Positioning Mode: Kinematic	Frequencies / Filter Type: L1 / Forward	Elevation Mask (?) / SNR Mask (dBHz): 15	Rec Dynamics / Earth Tides Correction: OFF / OFF	Ionosphere Correction: Broadcast	Troposphere Correction: Saastamoisen	Satellite Ephemeris/Clock: Broadcast
<input type="checkbox"/> Sat PCV <input type="checkbox"/> Rec PCV <input type="checkbox"/> Ph-Windup <input type="checkbox"/> Reject Ed <input type="checkbox"/> RAIM FDE <input checked="" type="checkbox"/> GPS <input type="checkbox"/> GLO <input checked="" type="checkbox"/> Galileo <input checked="" type="checkbox"/> QZSS <input checked="" type="checkbox"/> SBAS <input checked="" type="checkbox"/> BeiDou						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

**Options Dialog (highlighted in green):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Integer Ambiguity Res (GPS/GLO/BDS): Insta	Min Ratio to Fix Ambiguity: 3.0	Min Confidence / Max FCB to Fix Amb: 0.9999	Min Lock / Elevation (?) to Fix Amb: 0	Min Fix / Elevation (?) to Hold Amb: 10	Outage to Reset Amb / Slip Thres (m): 5	Max Age of Diff (s) / Sync Solution: 30.0
<input type="checkbox"/> Baseline Length Constraint (m)						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

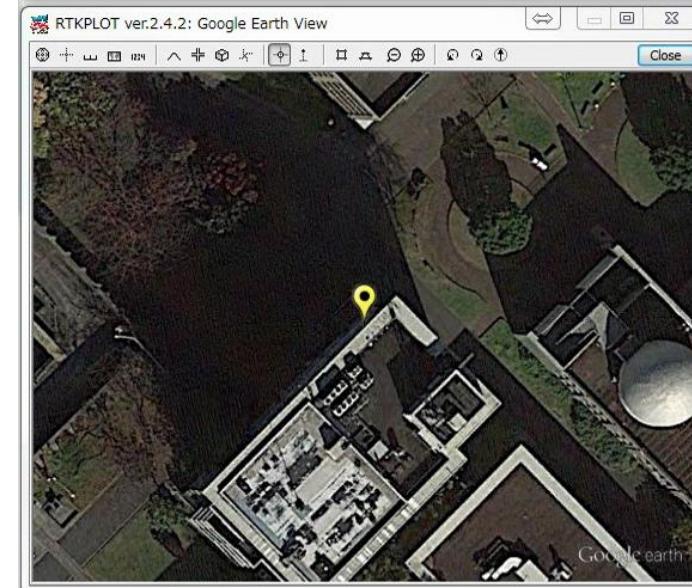
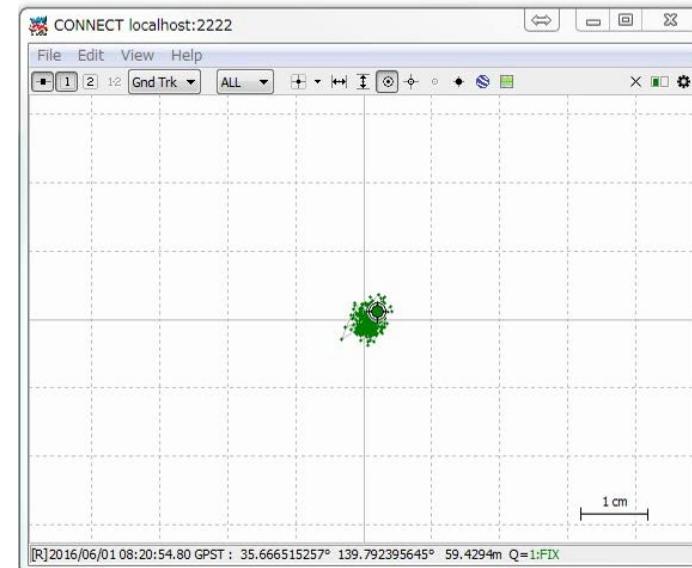
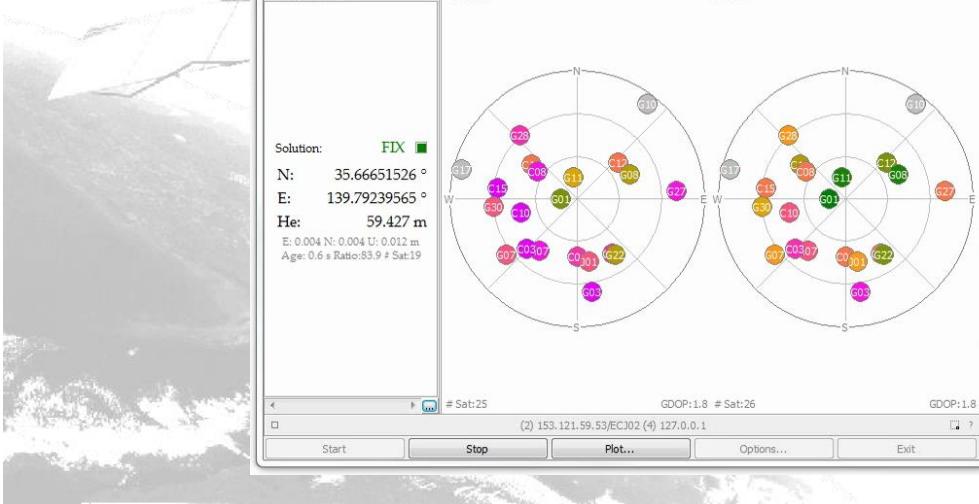
**Options Dialog (highlighted in green):**

Setting1	Setting2	Output	Statistics	Positions	Files	Misc
Rover	Lat/Lon/Height (deg/m): -90.000000000	Delta-E/N/U (m): -6378137.0000	Antenna Type (*: Auto)	Base Station	Lat/Lon/Height (deg/m): 35.66634219	Delta-E/N/U (m): 139.7922101
<input type="checkbox"/> Antenna Type (*: Auto)						
<input type="button"/> Load <input type="button"/> Save <input type="button"/> OK <input type="button"/> Cancel						

**Labels:**

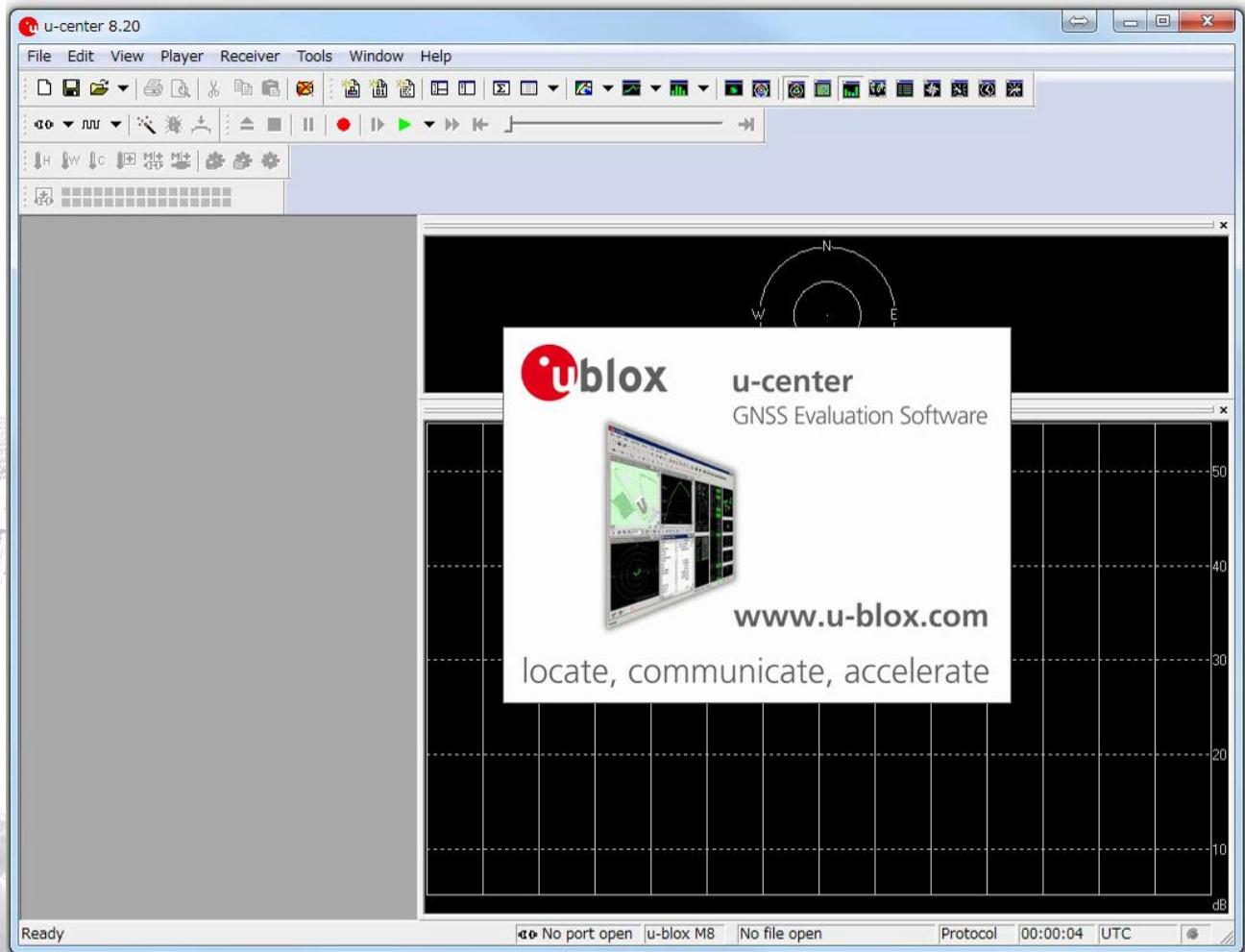
- kinematic=RTK 使用衛星群
- ARの解き方
- 基準局真値入力

# RTKNAVI : Processing results



# U-center : Receiver configuration settings

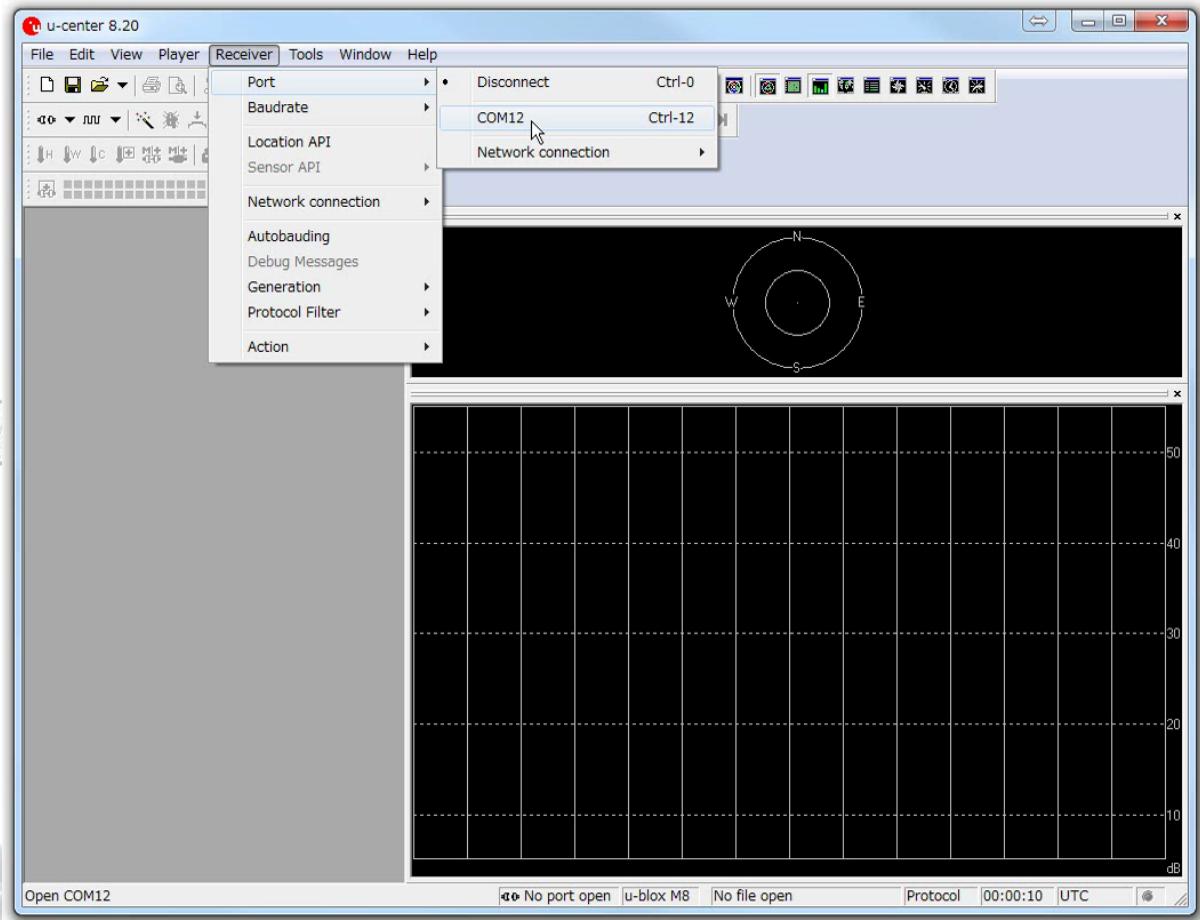
- Start U-center ver. 8.20 or later



# U-center : Receiver configuration settings

- Connecting

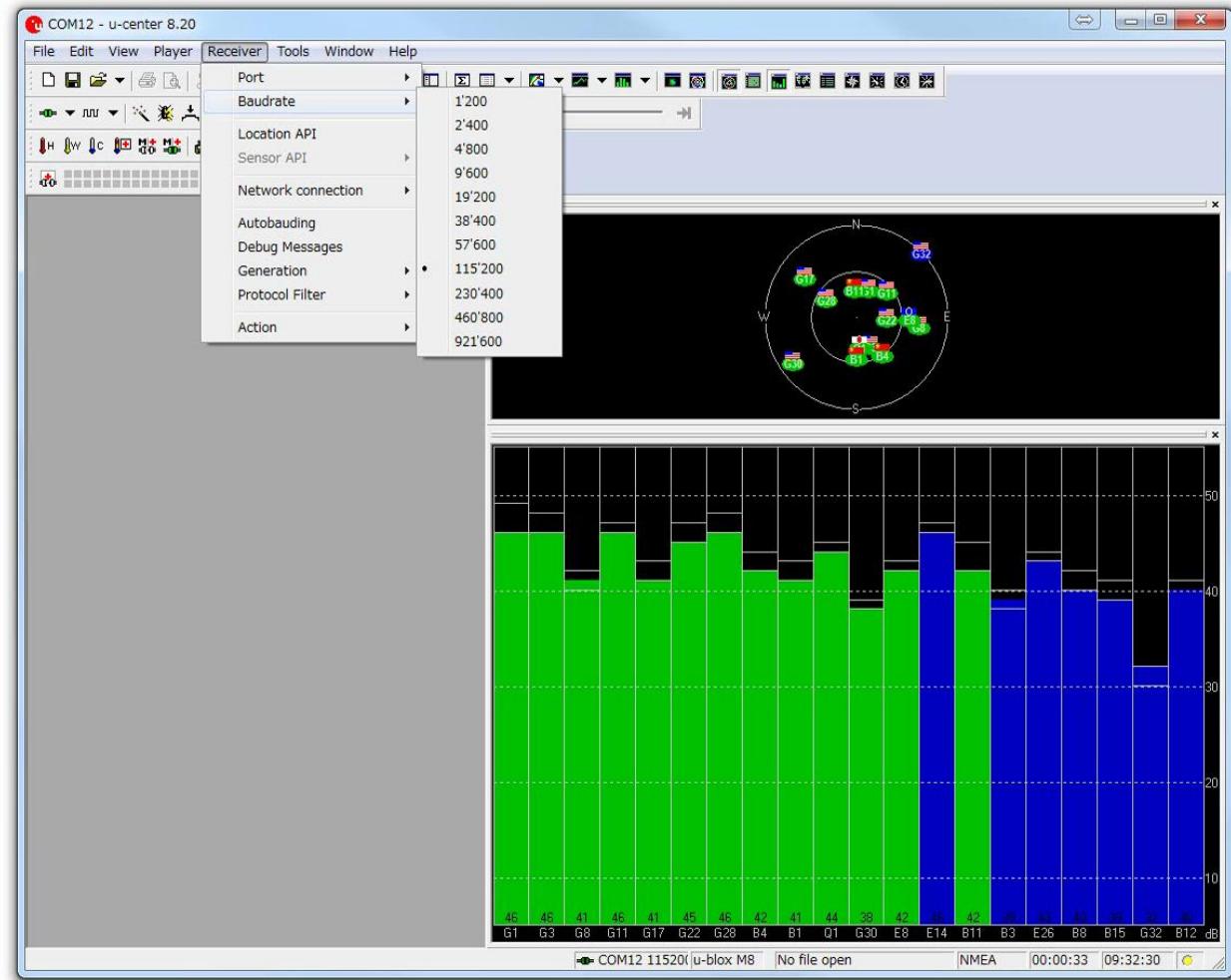
Receiver->Port-> Select receiver port number



# U-center : Receiver configuration settings

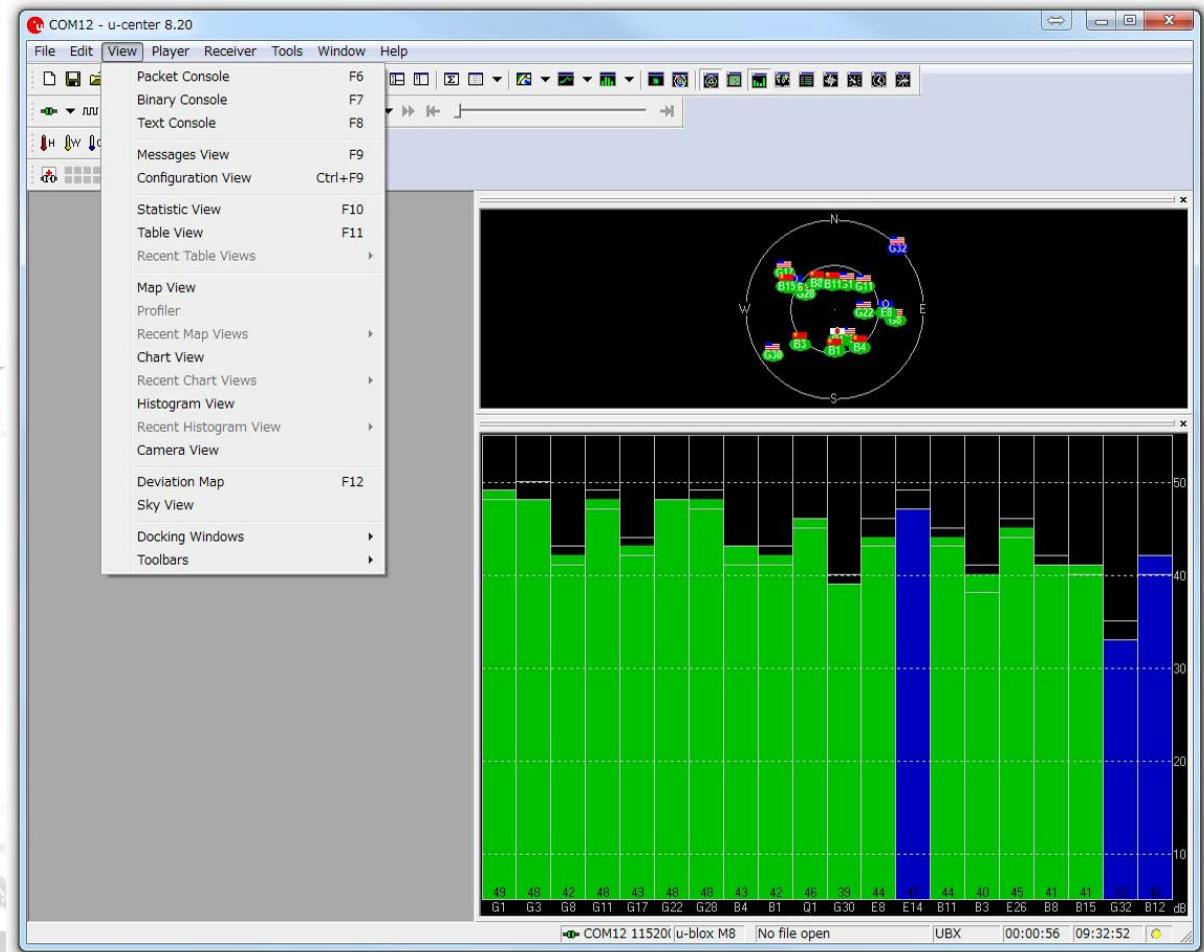
- Set USB Baud rate

Receiver->Baudrate (Recommendation: 115200)



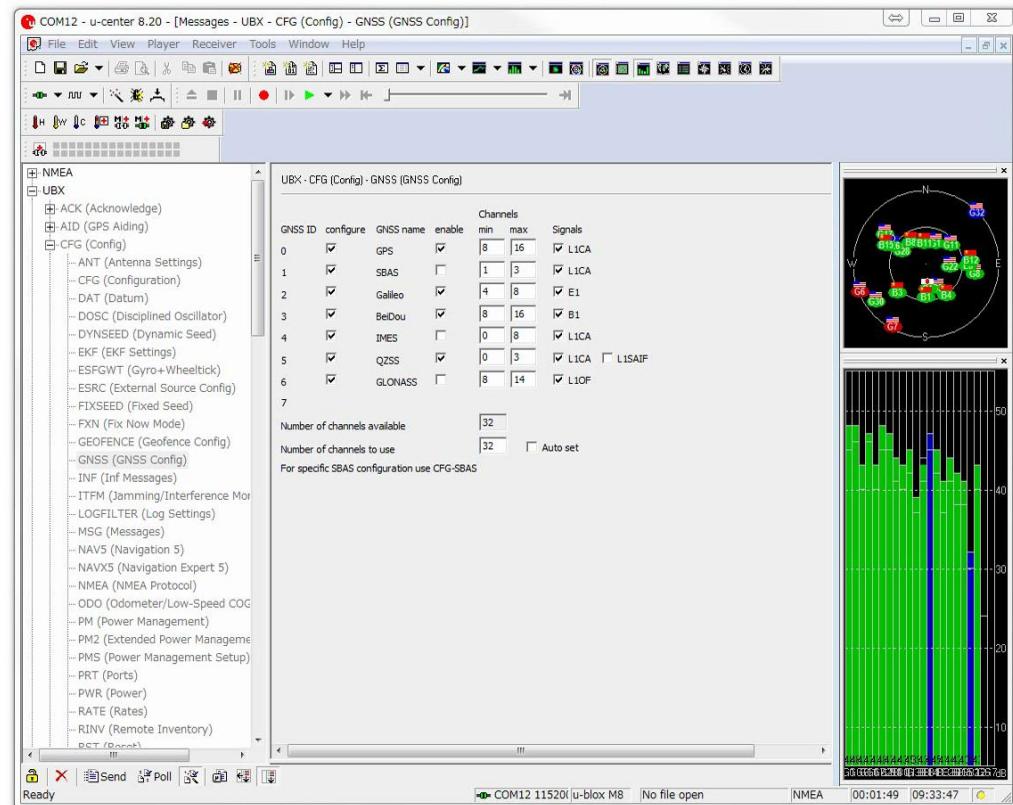
# U-center : Receiver configuration settings

- Set detailed configuration settings
- View->message view (see next slide)



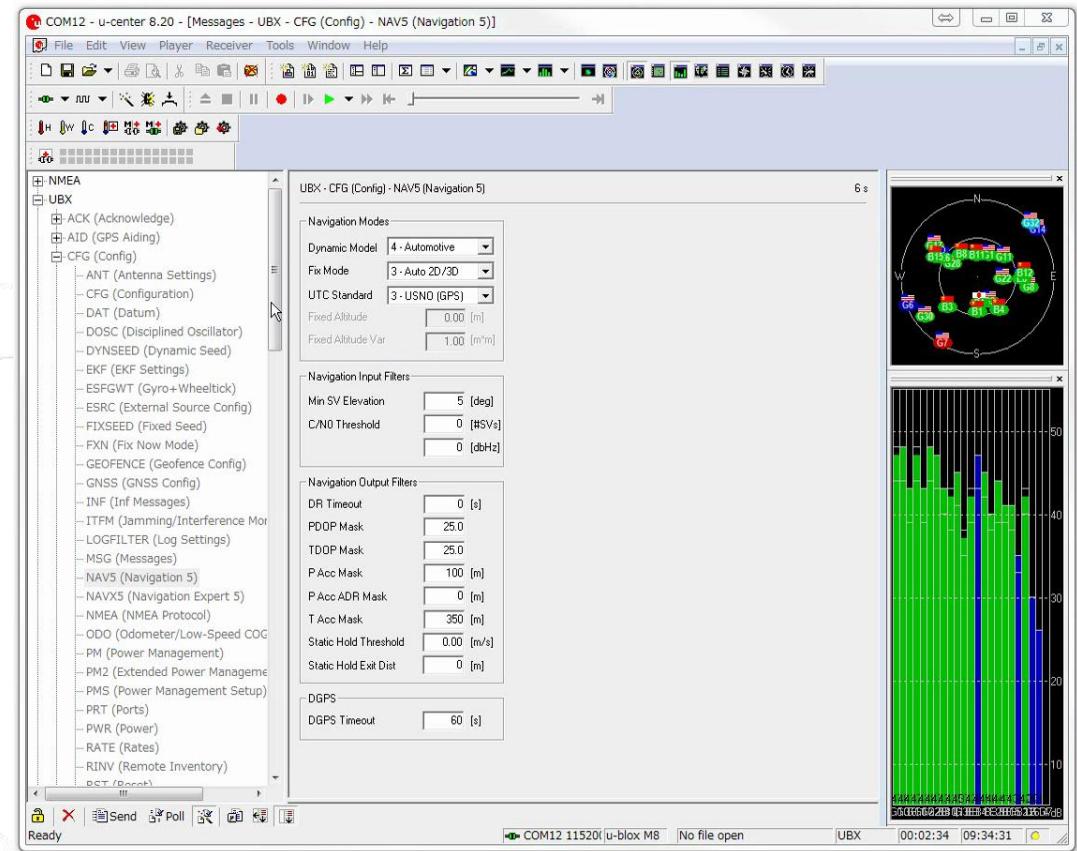
# U-center : Receiver configuration settings

- Select satellites
  - UBX->CFG->GNSS
  - Cannot use GLONASS and Beidou at the same time
  - After changing Configuration, click Send



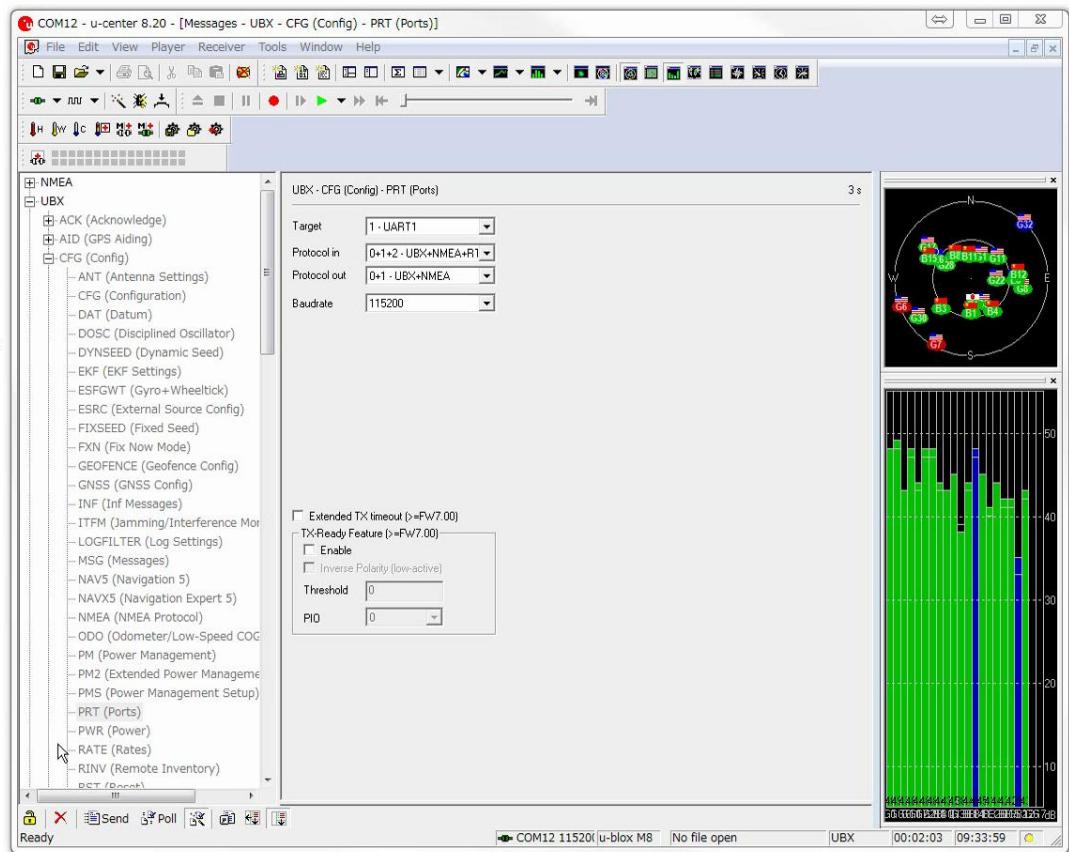
# U-center : Receiver configuration settings

- Change NMEA data mode
  - UBX->CFG->NAV5
  - After changing Configuration, click Send



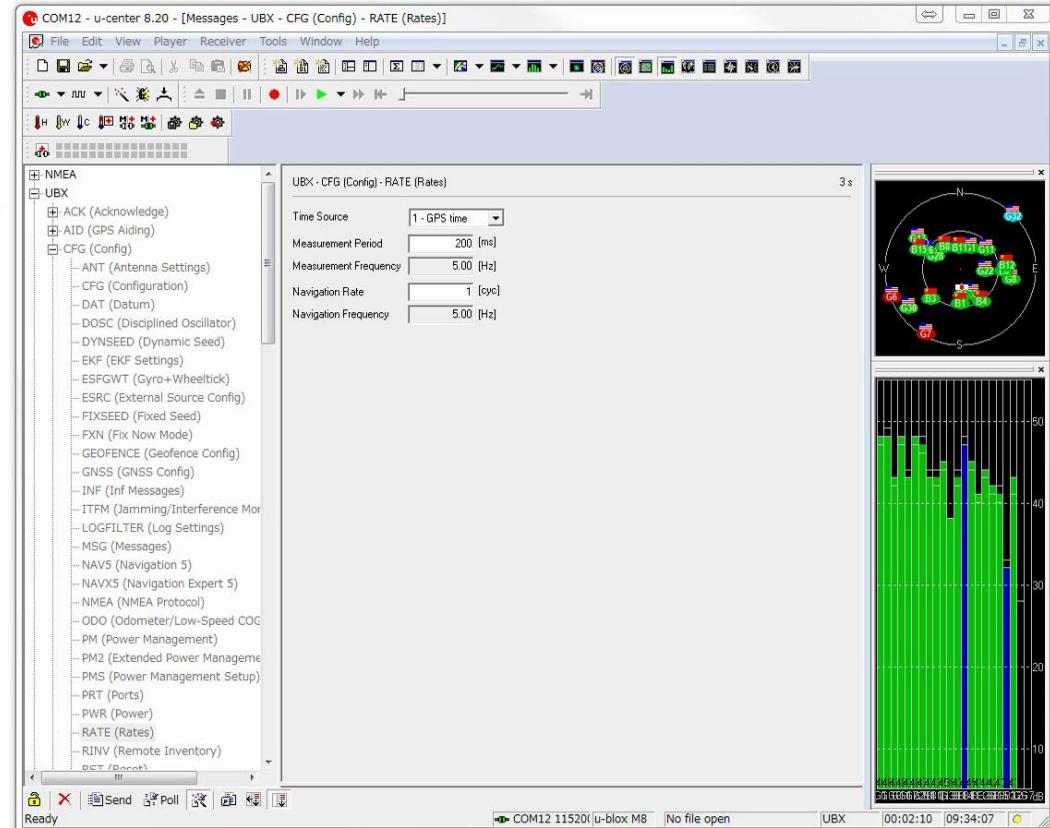
# U-center : Receiver configuration settings

- Confirm output of each port
  - UBX->CFG->PRT
  - Baud rate and UART are the same as for USB (ex. 115200)



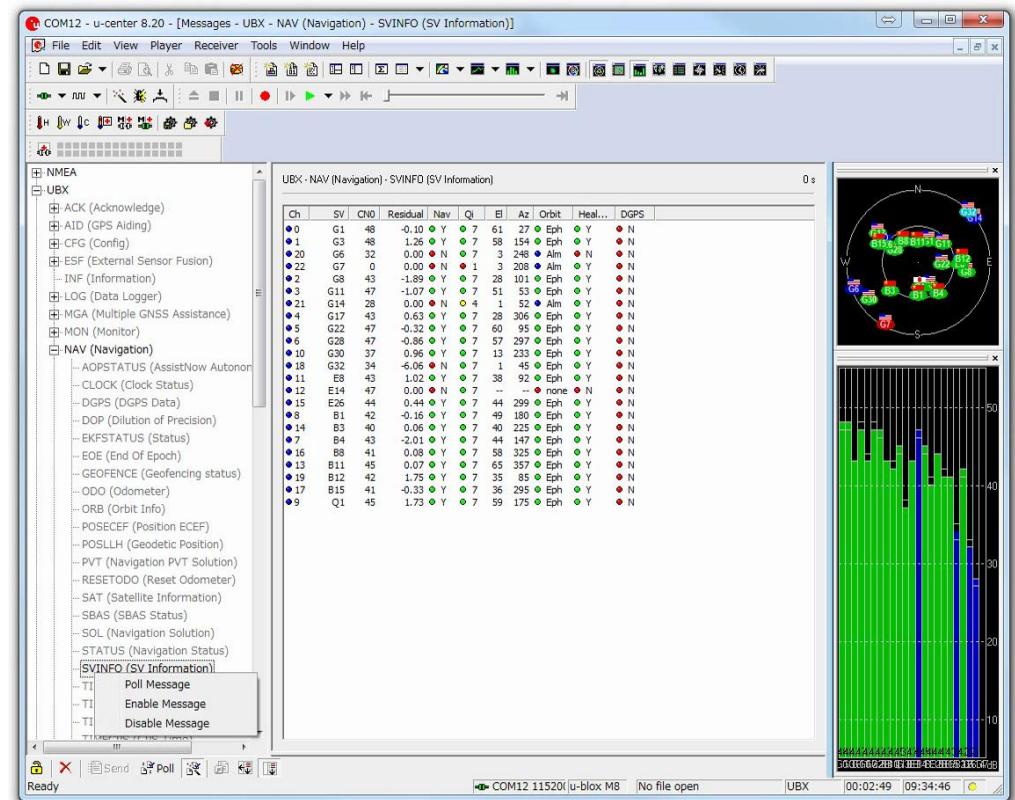
# U-center : Receiver configuration settings

- Setting output data interval (data rate)
  - UBX->CFG->RATE
  - ( 200 ms = 5 Hz)



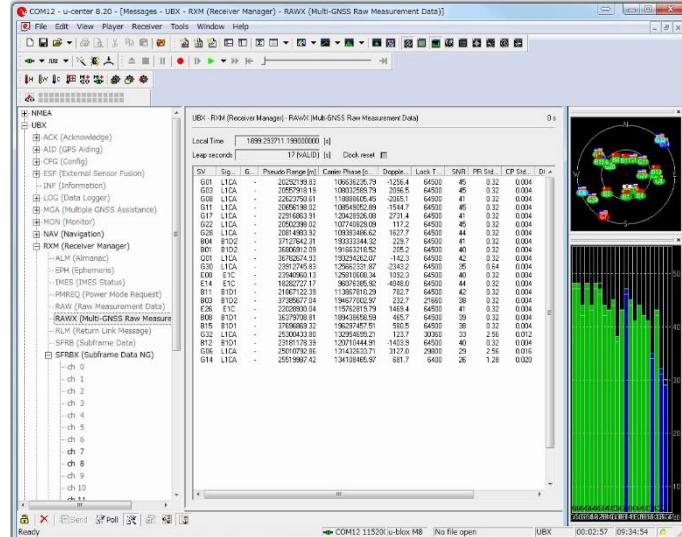
# U-center : Receiver configuration settings

- Output SVINFO (recommended)
  - UBX->NAV->SVINFO
  - Right click SVINFO->Enable SV information Message & Poll Message



# U-center : Receiver configuration settings

- Output RAWX (obs file)
  - UBX->RXM->RAWX
  - Right click RAWX
    - Enable Message & Poll Message
- Output SFRBX (nav file)
  - UBX->RXM->SFRBX
  - Right click SFRBX
    - Enable Message & Poll Message
- This data is used by RTKNAVI



# U-center : Receiver configuration settings

- Save receiver configuration
- Receiver->Action->Save config
- After setting and saving, Close u-center

