

# Effective Satellite Selection Methods for RTK-GNSS NLOS Exclusion in Dense Urban Environments

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The Geographical Survey Institute carried out this study as a general technology development project of the Ministry of Land, Infrastructure and Transport minister's secretariat technology Security Research Division.

# Background

## Satellite positioning and construction

High accurate satellite positioning solution



Construction

Smart construction by **KOMATSU**



Intelligent construction by **Leica Geosystems**



# Background

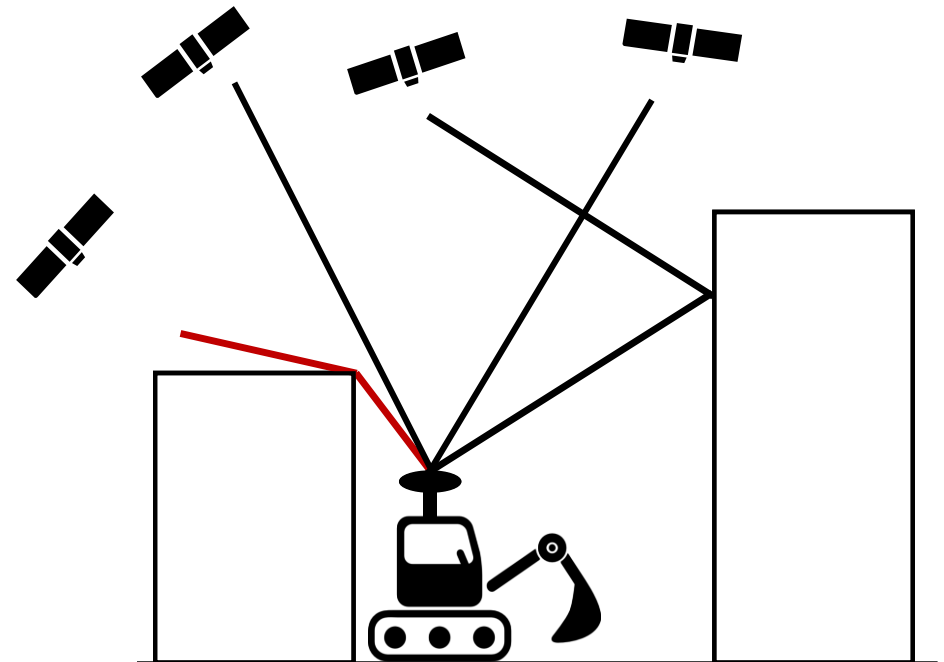
## Issues of satellite positioning in urban environment



Urban construction

1. Received Multipath signals

2. Lack of visible satellites



# Background

## Multipath effects in dense urban environment

DGNSS solutions  
Google map



Huge errors

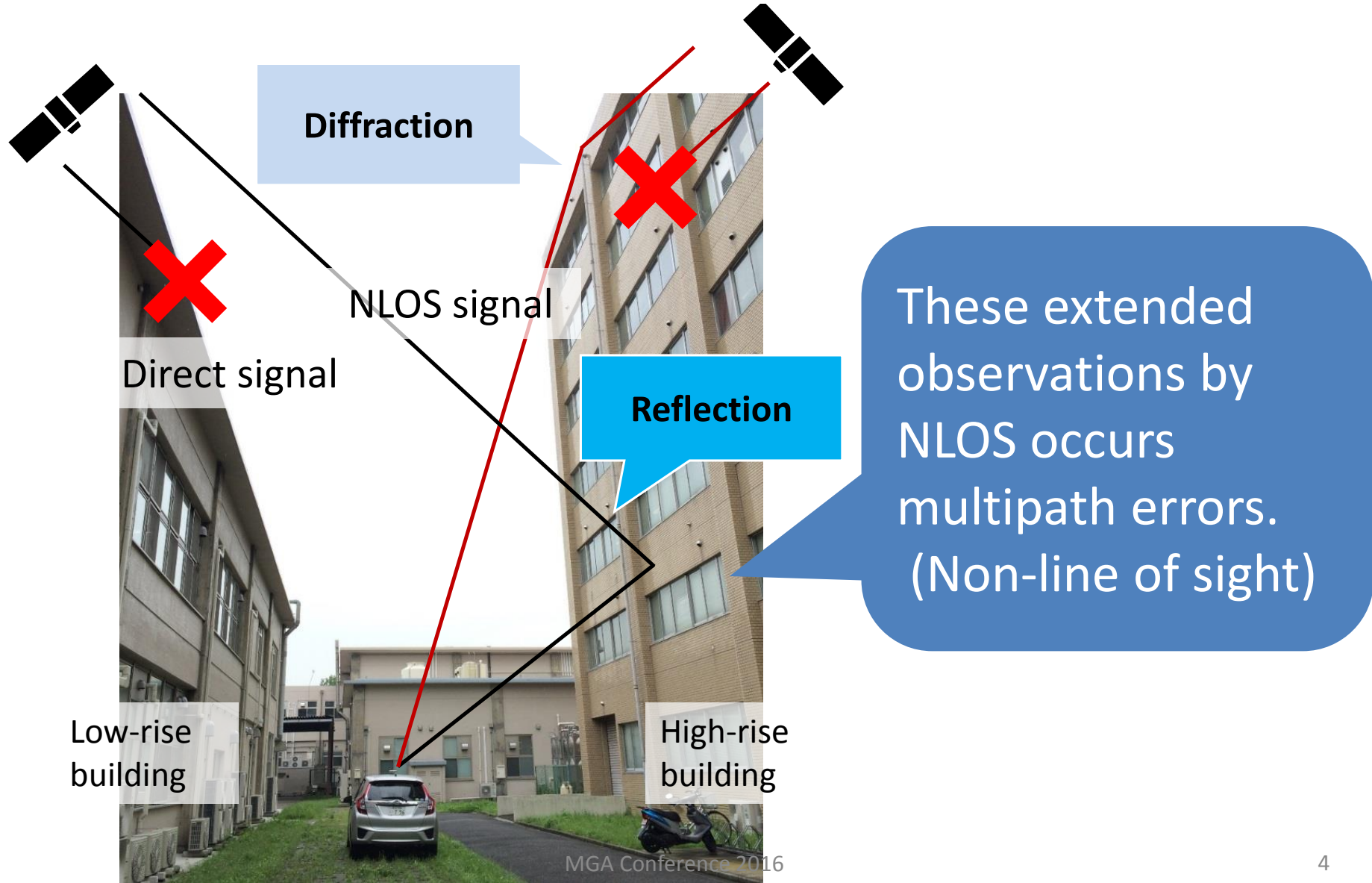
Testing course  
Google earth



Caused by high-rise buildings

# Background

## Details of multipath effects (images)

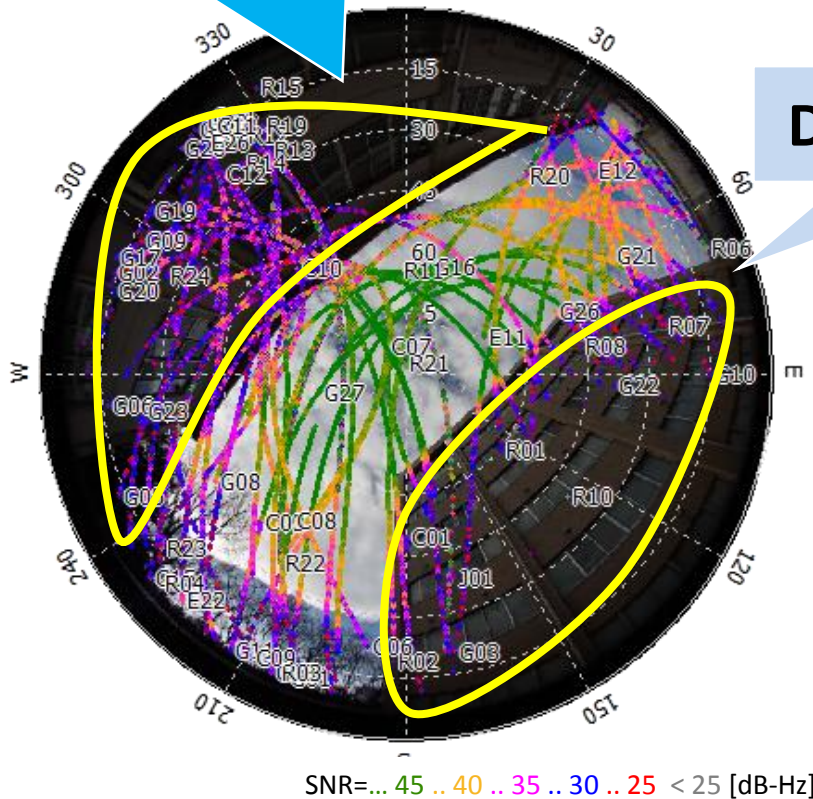


# Background

## Details of multipath effects (by actual data)

Observed signal strength with sky view

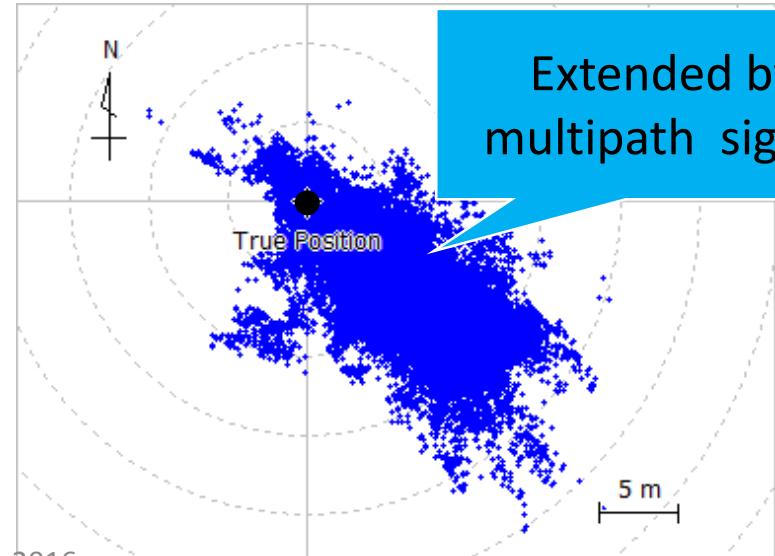
**Reflected signals**



**Diffracted signals**

**Results of DGNS**

12hours DGNS solution



# Background

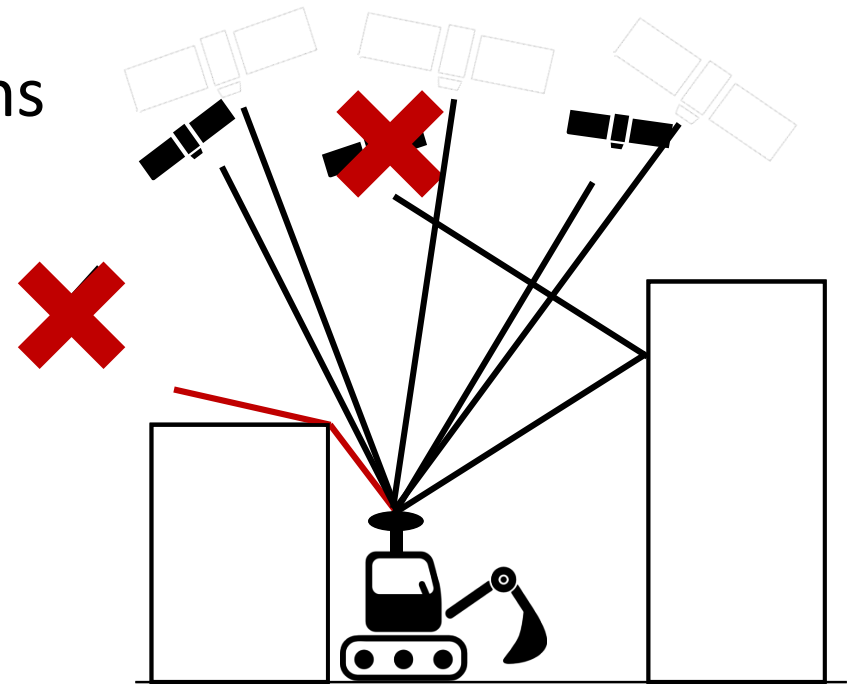
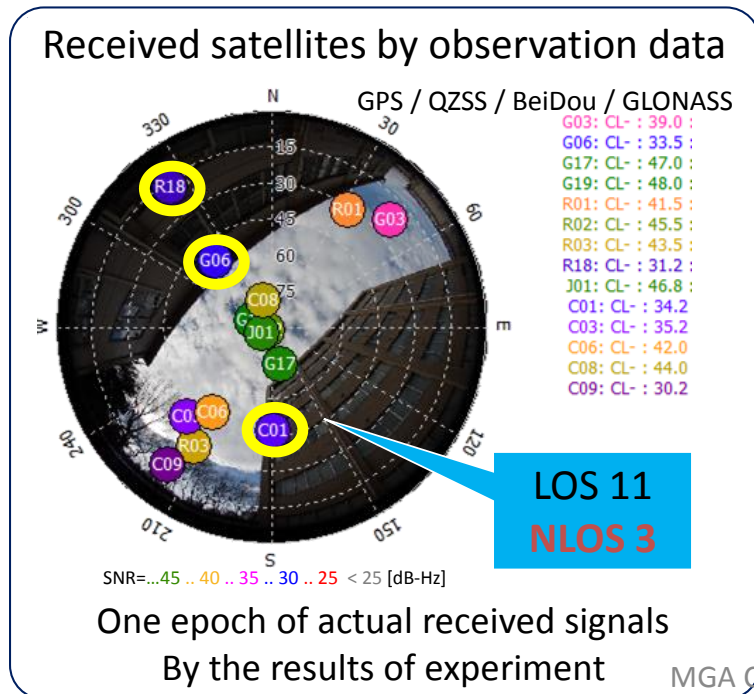
## Based on two ideas

1. Received Multipath signals

→ **Satellite selection** to exclude NLOS satellite

2. Lack of visible satellites

→ Use multiple constellations



→ chance to improve positioning performance  
using satellite selection method

# Background

## Conventional satellite selection methods

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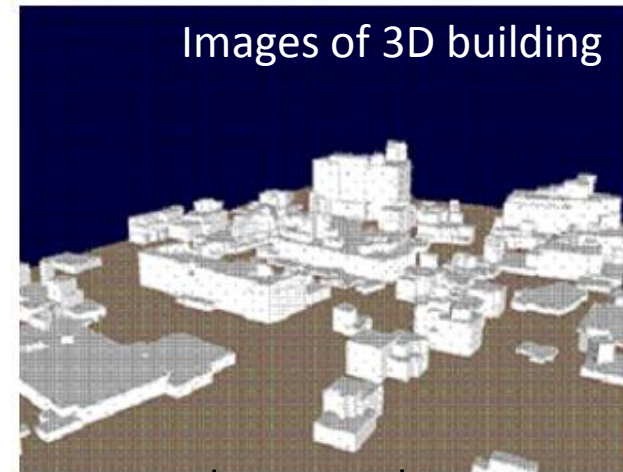
- The fisheye view image has been used for several researches

Suzuki, T., Kitamura, M., Amano, Y., and Hashizume. High-accuracy GPS and GLONASS positioning by multipath mitigation using omnidirectional infrared camera. ICRA 2011

- Precise 3D building maps are being developed by companies and used for multipath mitigation

Hsu, L. T., GU, Y., and Kamijo, S., 3D building model-based pedestrian positioning method using GPS/GLONASS/QZSS and its reliability calculation. GPS Solutions, 1-16.ISO 690

Groves, Paul D., et al. Intelligent urban positioning using multi-constellation GNSS with 3D mapping and nlos signal detection. 2012



- These methods are mainly discussed for kinematic data with code based positioning

→ We try to apply these methods for RTK-GNSS

- Signal strength observation to detect the multipath signal

Suzuki, T., Kubo, N., and Yasuda, A., The possibility of the precise positioning and multipath error mitigation in the real-time. In The 2004 International Symposium on GNSS/GPS



# Objective

## Performance improvement for surveying



Target: Multipath mitigation for **surveying**

- cm-level positioning (**RTK-GNSS**)
  - Use of Multi constellation GNSS
  - Static positioning
- 
- Evaluation of conventional studies of satellite selection method for High accurate positioning (RTK-GNSS)
    1. Mask based on **fish-eye view image**
    2. Mask based on precise **3D-map**
    3. Mask based on **SNR measurements**

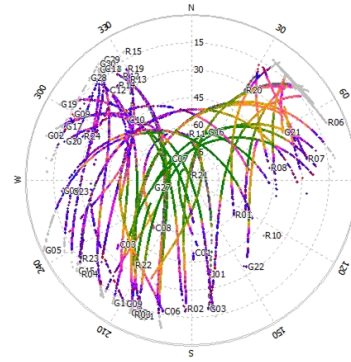
# Outline

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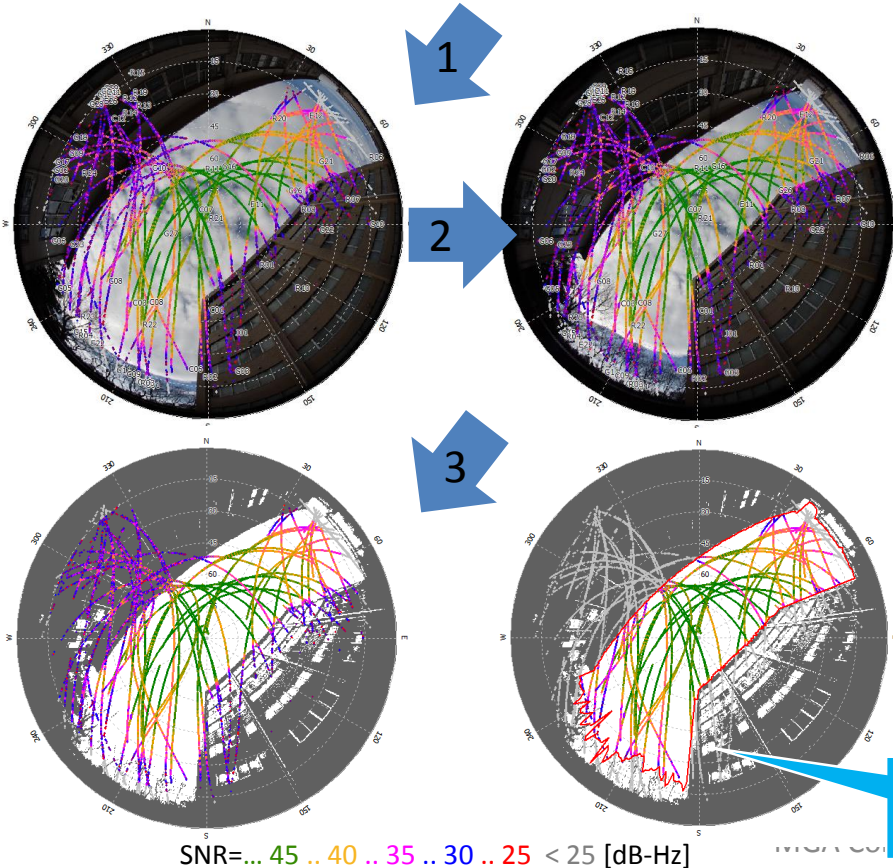
1. Background and objective
2. Conventional satellite selection methods
3. Testing and results
4. Weakness of SNR and SNR based new method
5. Testing and results
6. Conclusions

# Conventional satellite selection methods

## 1. Fisheye view images based mask



Observed signal strength with equidistant projection



### Procedure for making mask

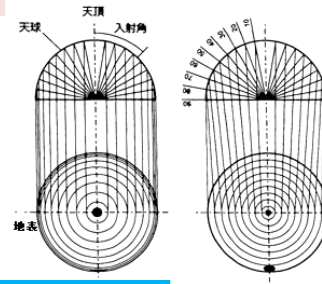
1. Azimuth adjustment
2. Projection adjustment  
checkerboard calibrating tools for the initialization
3. Mask Making  
Binaries the image



RTKLIB  
2.4.3 b5~

Open source software to make a mask with the fisheye view image

### Projection



Mask: Red line  
(Expressed by elevation for every 1 deg. Of azimuth)

# Conventional satellite selection methods

## 2. Precise 3D-map based mask

### Input data

- Precise 3D map (10cm accuracy)
- Estimated position by SPP  
(Several metres)

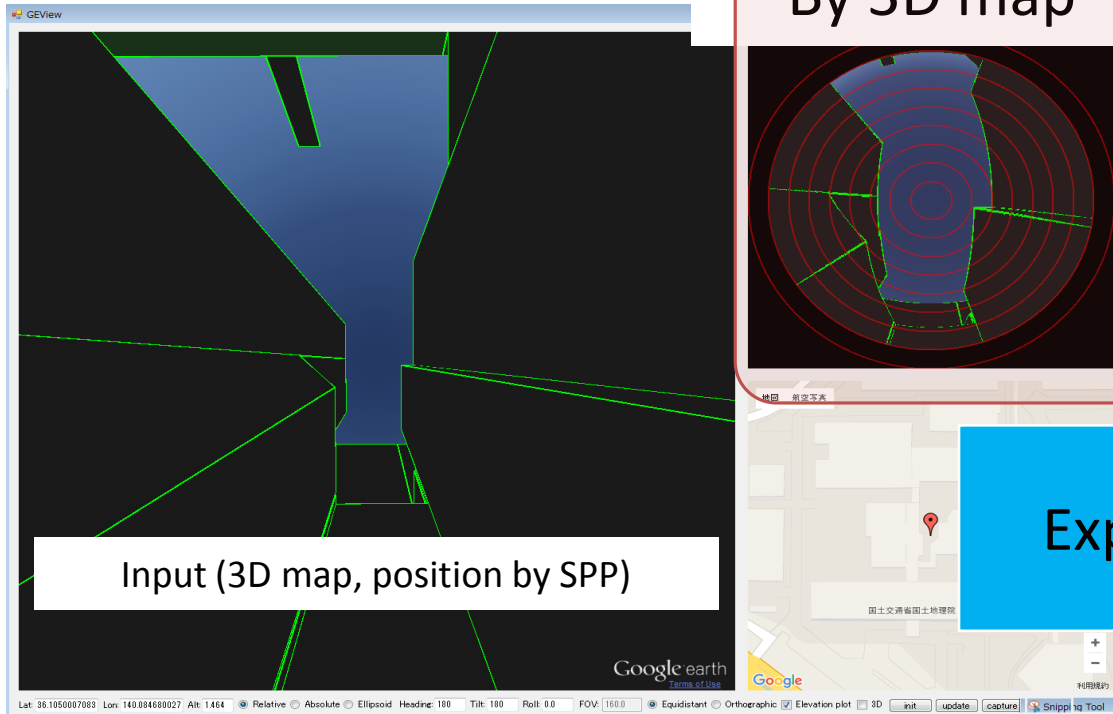


### Output data

- Sky obstacles mask

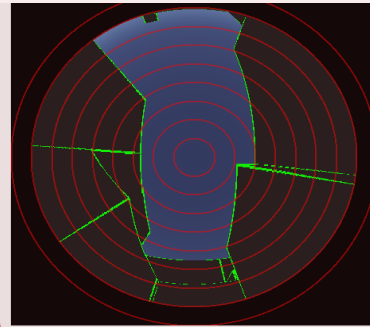
### Software

### Screen shot

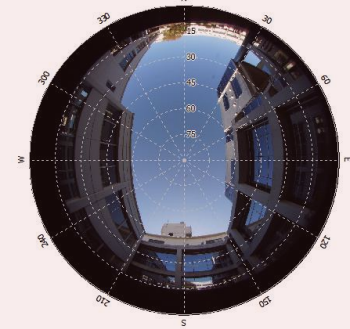


### Sky obstacles comparisons

#### By 3D map



#### By Fisheye view image

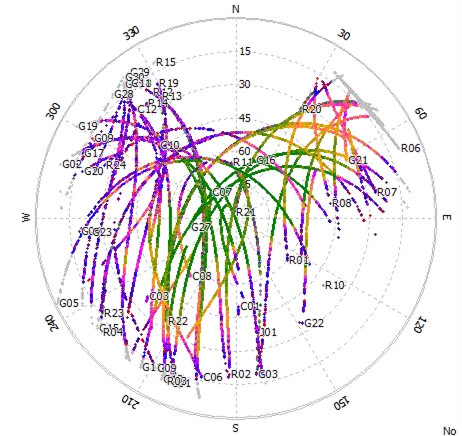
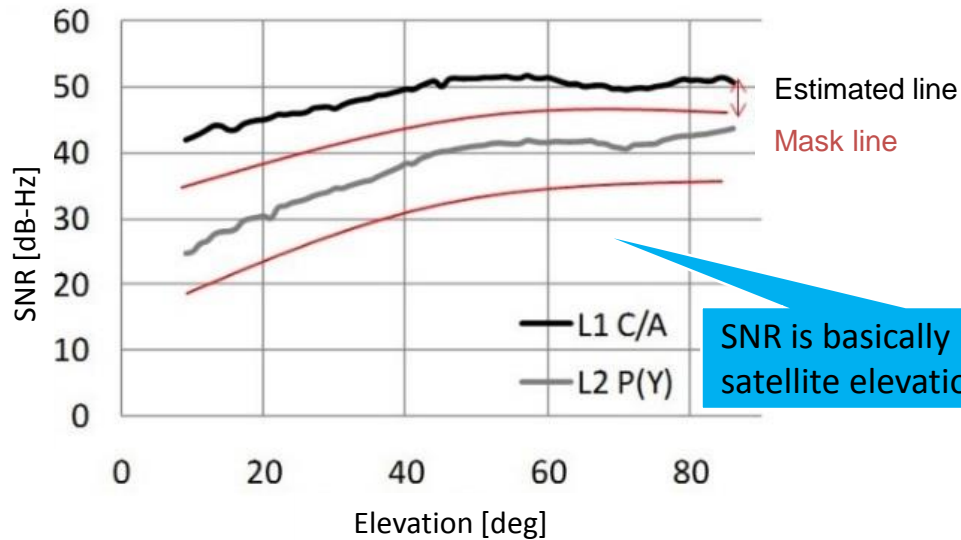


Expressed same tendency

# Conventional satellite selection methods

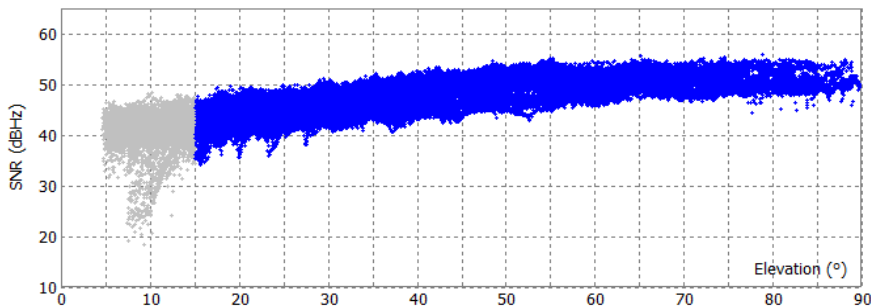
## 3. SNR observations quality check based mask

Elevation-SNR estimated line and Threshold line

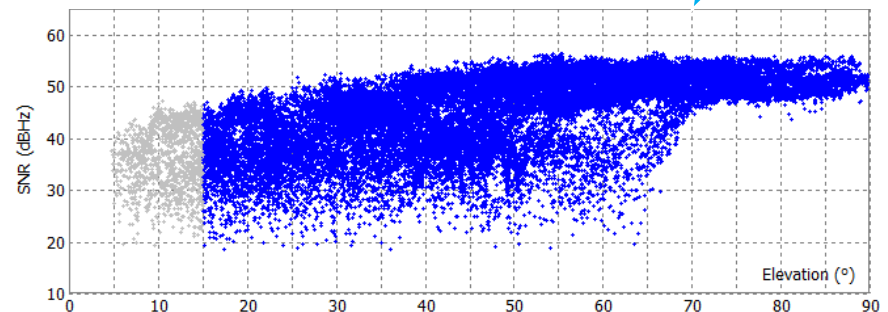


Multipath signal causes a reflection loss

24-hours SNR at base station (Open sky)



24-hours SNR at rover (Multipath environment)

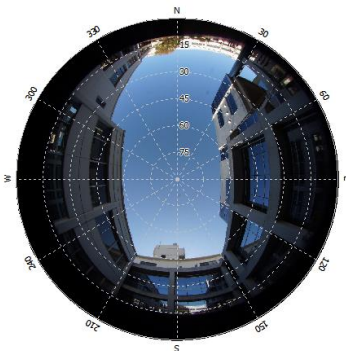


# Testing and results

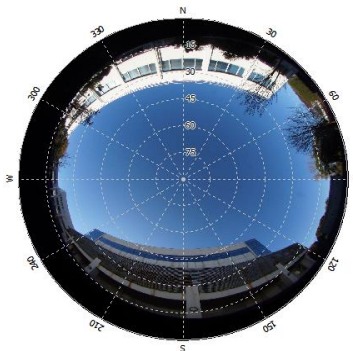
## Outline of experiments

Fisheye view pictures of each testing environment

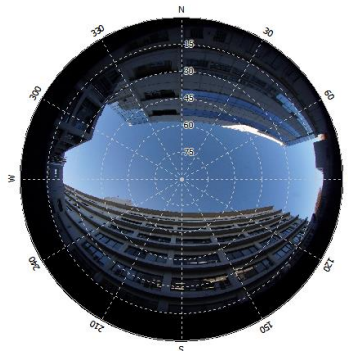
Point A



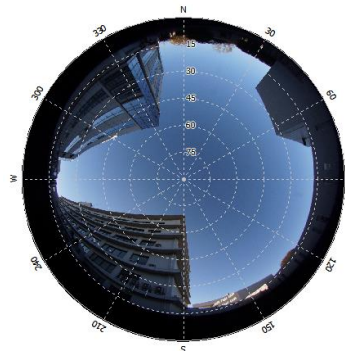
Point B



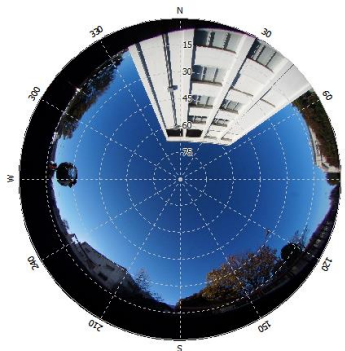
Point C



Point D



Point E



\* North side up

- Instantaneous RTK-GNSS  
(Without any filter, hold technique)
- Double frequency observations
- GPS/QZSS/BeiDou

Analyse conditions

AR: LAMBDA Methods with Ratio test  
(Fixed threshold for over 3)

Elevation mask: Over 15 degrees

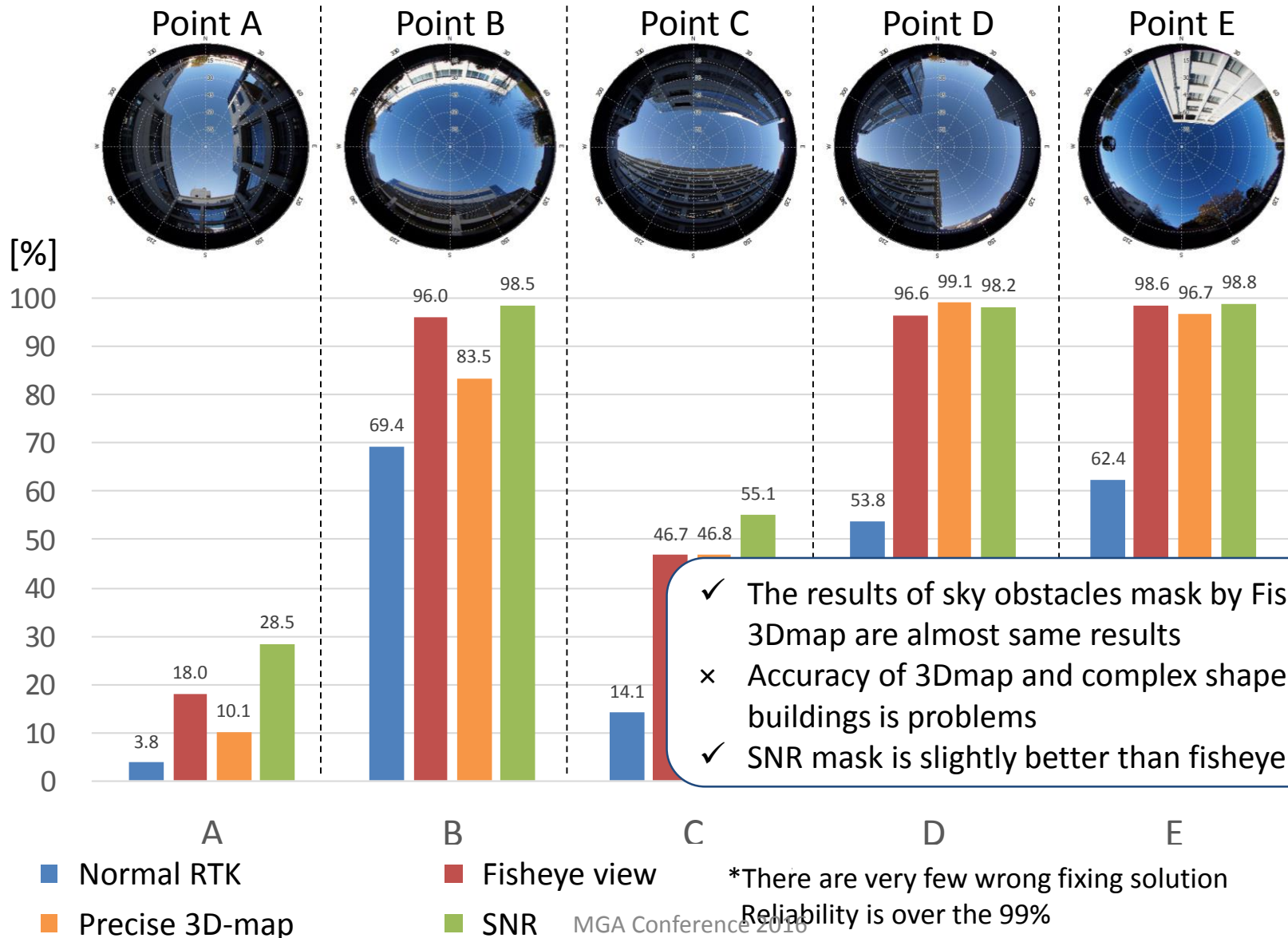
Short baseline (within 1 Km)

	24hours data at each point
Period	A 2015-12-09 07:09:30~ 12-10 07:05:30
	B 2015-12-22 07:53:30~ 12-23 07:53:00
	C 2015-12-09 07:09:30~ 12-10 07:09:00
	D 2015-12-21 06:54:00~ 12-22 06:53:30
	E 2015-12-21 06:54:00~ 12-22 06:53:30
Receivers	Base / Rover : JAVAD DELTA
Antenna	JAVAD GrAnt-G3T

# Testing and results

## Availability results of each point

$$\text{Availability} = \frac{\text{Fix solution}}{\text{Total epoch}}$$



# Testing and results

## Characteristic for the methods

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### 1. Fisheye view mask

- ✓ Density of sky obstacles for both buildings and trees
- ✓ More realistic: same environment as antenna
- × Making mask procedure is manually
- × Initial correction for each lens to adjust projection
- × Not realistic

### 2. Precise 3D map mask

- ✓ Making masks automatically in advance
- × Trees, distant buildings and complicated shape buildings
- × Depends on accuracy of input position and 3Dmap
- × Limited to the place that exist of precise 3Dmap

### 3. SNR mask

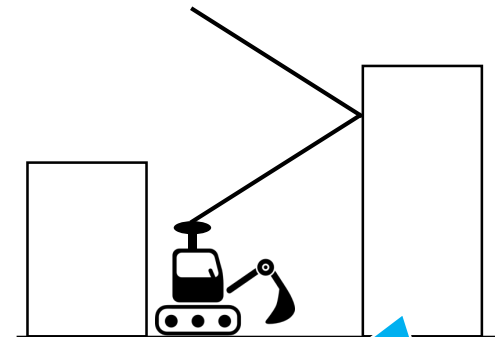
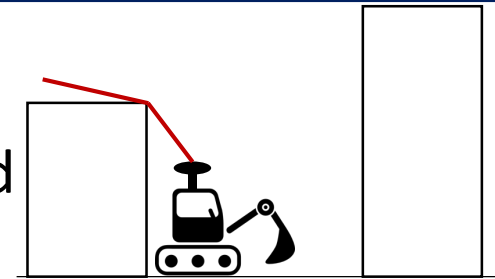
- ✓ No need for external data
- × Preparation for each estimated line of receiver and satellite systems



# Testing and results

## Weakness of SNR based mask

- Diffracted signals by NLOS
  - As a result of previous experiments, diffracted signals can be excluded correctly.
- Reflected signals by NLOS
  - However, **there is the situation that received strong reflected signals by NLOS**
  - SNR mask is difficult to detect these reflected signals



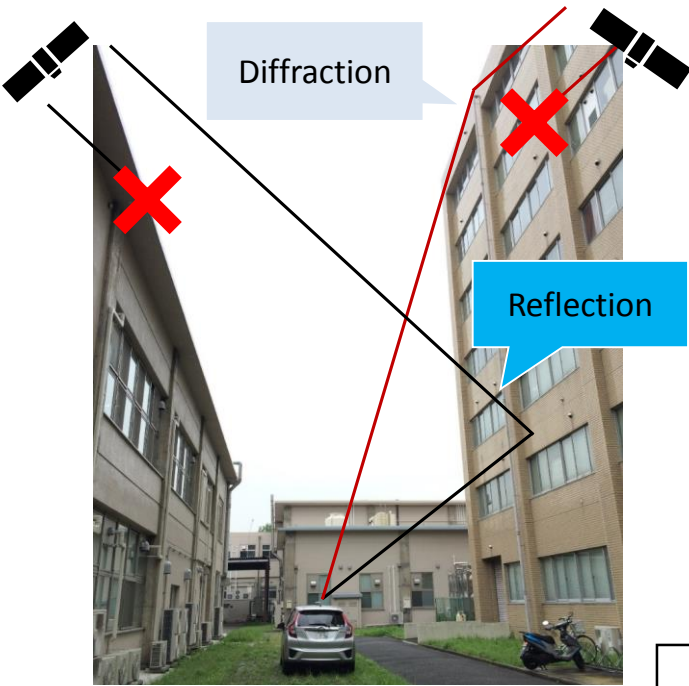
Strong reflected signals are difficult to mitigate



- We investigated to know the proper performance under this situation

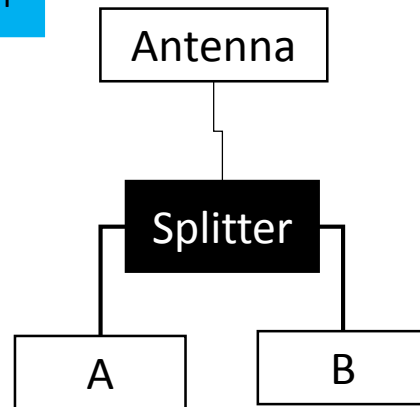
# Testing and results at NLOS environments

## Outline of new experiments



Testing environment

Specific environment that the receivers force to receive strong reflected signal by NLOS satellites



Conditions

- Instantaneous RTK-GNSS (Without any filter, hold technique)
- Double frequency observations for **GPS/QZSS/BeiDou/GLONASS**

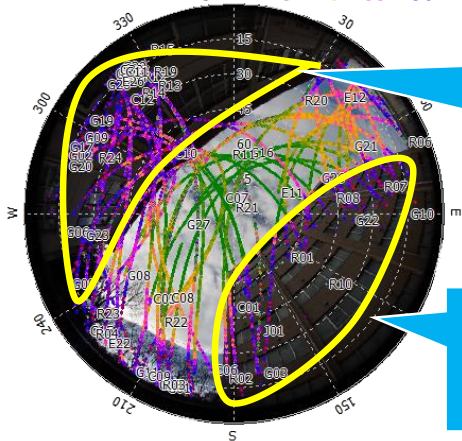
Analyse conditions

- AR: LAMBDA Methods with Ratio test (Fixed threshold for over 3)
- Elevation mask: Over 15 degrees
- Short baseline (within 1 Km)
- Receiver Base/Rover: A, B

Satellite selection methods

1. Fisheye view mask
2. SNR mask

SNR=...45 .. 40 .. 35 .. 30 .. 25 < 25 [dB-Hz]

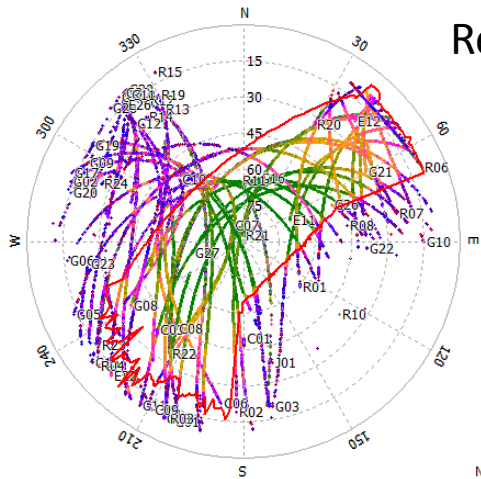


Powerful reflected signals were contentiously received

Diffracted signals are relatively few

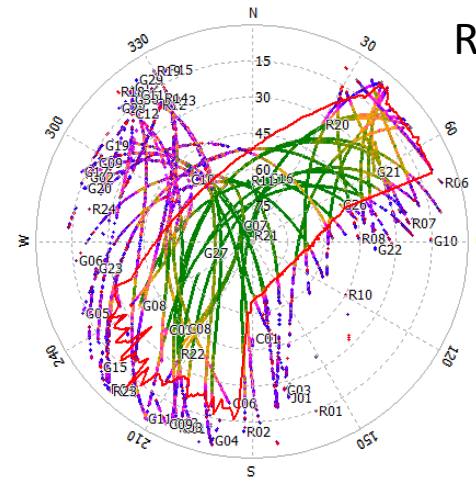
# Testing and results at NLOS environments

## Availability results of both receivers



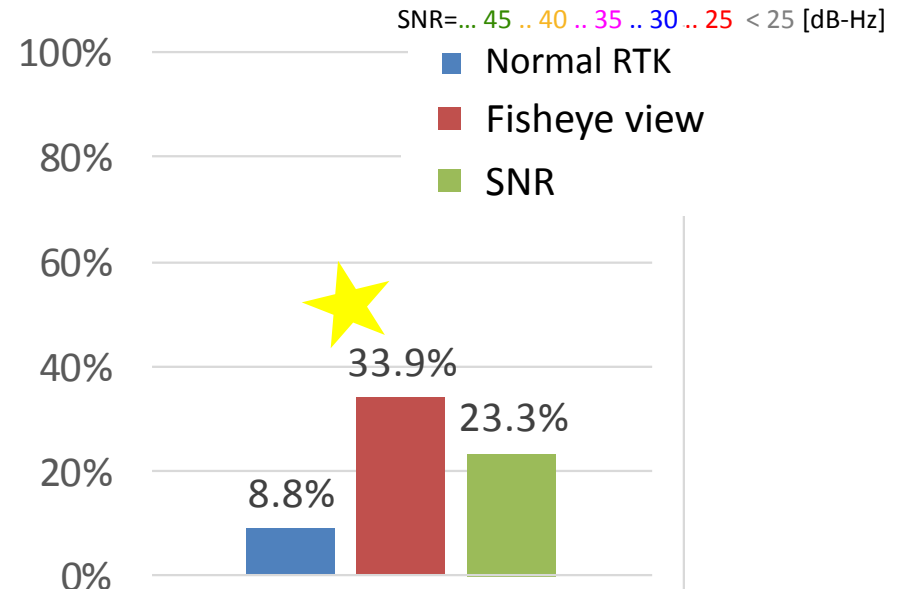
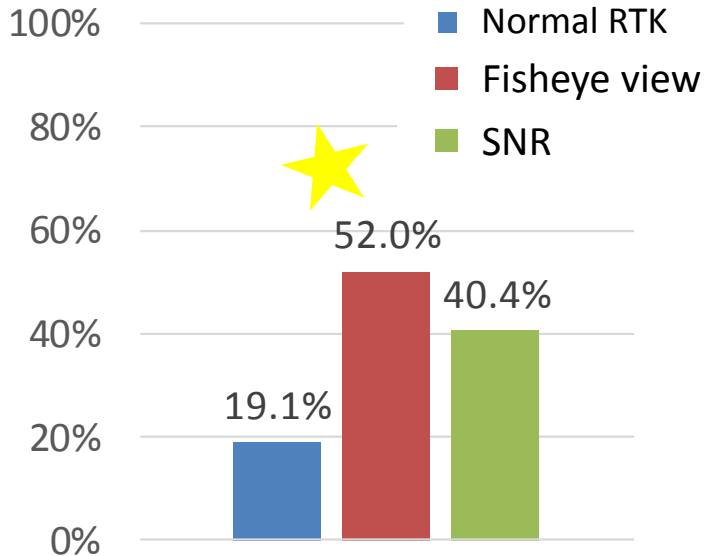
Receiver A

Ave SV  
All 11.4  
GJ 4.3  
C 3.8  
R 3.3



Receiver B

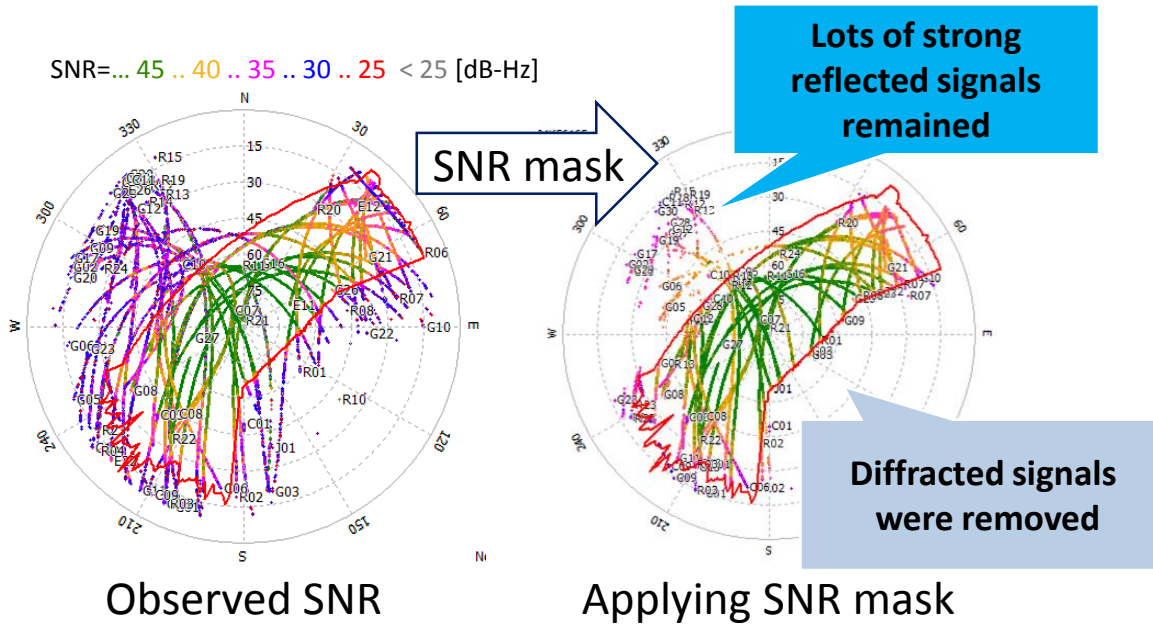
Ave SV  
All 12.4  
GJ 4.7  
C 3.8  
R 3.8



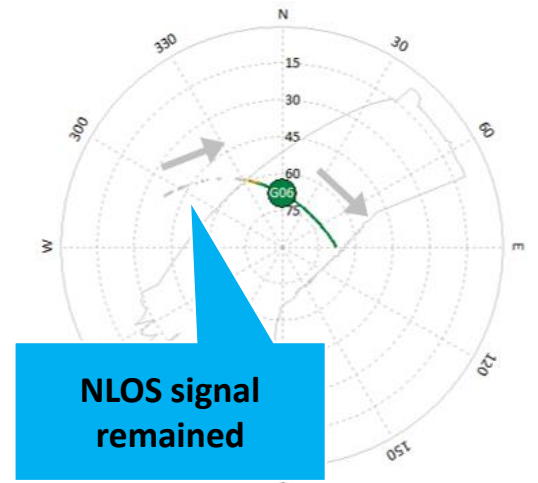
- ✓ As expected, Fisheye view mask is more efficient to exclude multipath signal
- we investigated the remaining observations after the applying SNR mask to compare the fisheye view mask

# Testing and results at NLOS environments

## Remaining SNR observations of reflected signal



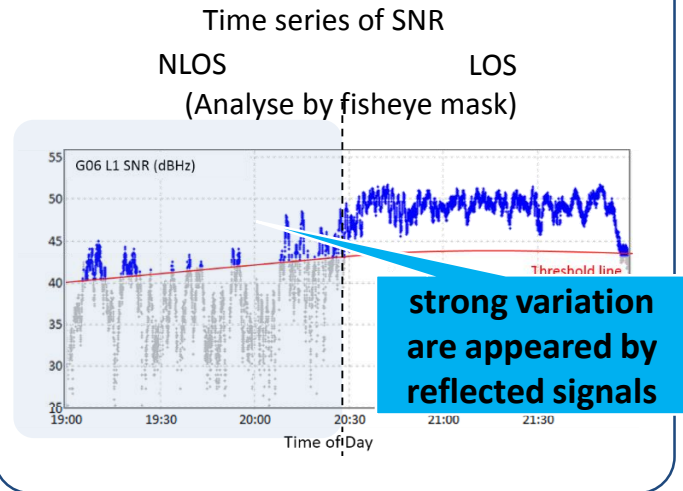
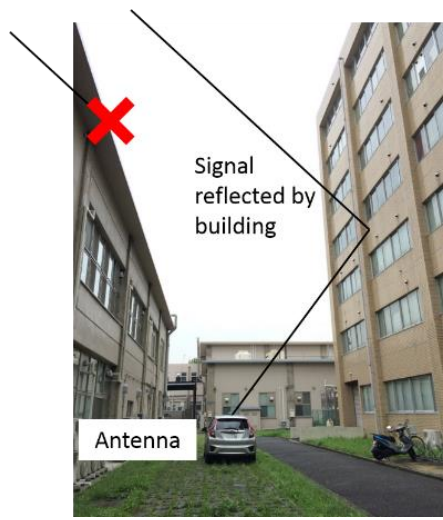
### Strong reflection signal



The remaining SNR was analyzed based on fisheye view mask

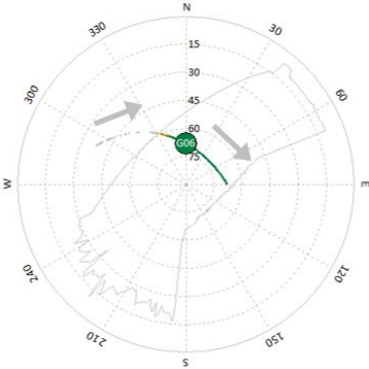
- Conventional SNR mask cut off lower SNR below the line

Improved satellite selection method focused on variation



# Testing and results at NLOS environments

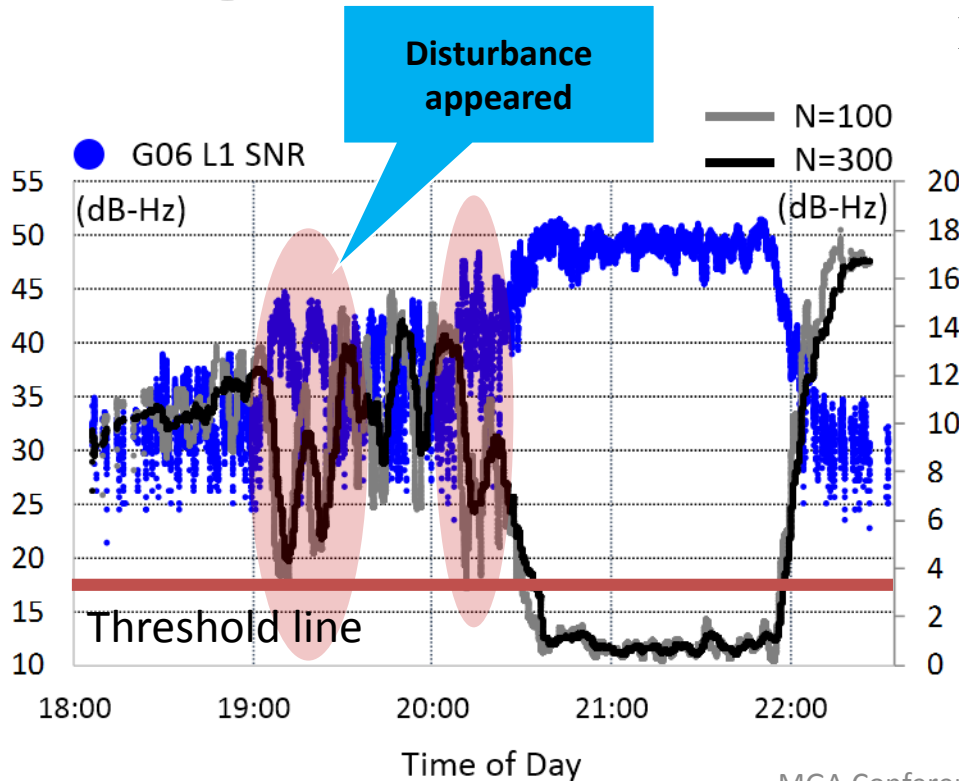
## Proposed new SNR based satellite selection methods



$$v(t_i) = SNR(t_i)_{ele} - SNR(ele) \quad (1)$$

$$V(t_i) = \sqrt{\frac{1}{N} \sum_{i=1}^N (v(t_i))^2} \quad (2)$$

N is the averaging window size.



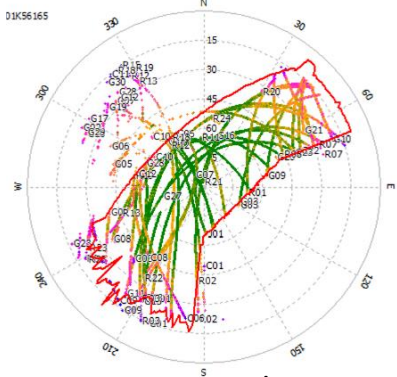
1. Take the difference between Estimated SNR line and observed SNR (1)
  2. Calculate the backward moving average over the N epoch (2)
- ✓ Huge SNR degradation is able to be distinguished
  - ✓ Effectively for continuously received reflected signal

# Testing and results at NLOS environments

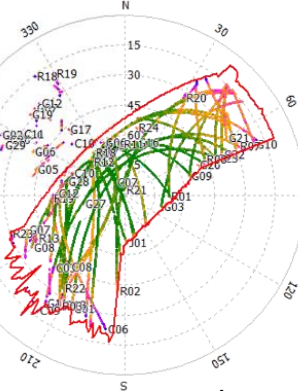
## New results of proposed method

SNR=... 45 .. 40 .. 35 .. 30 .. 25 < 25 [dB-Hz]

Receiver A

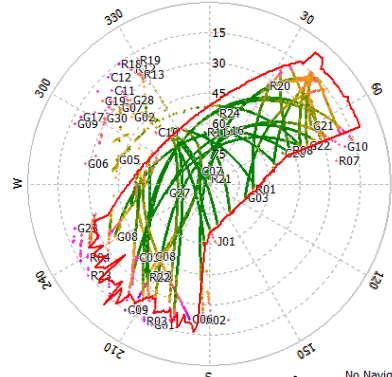


SNR mask



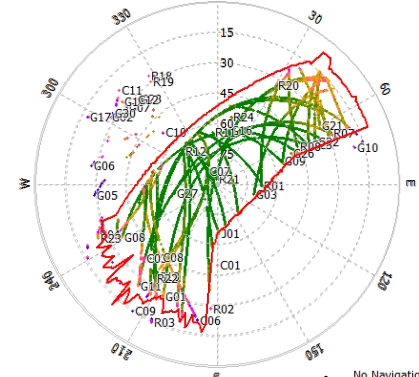
New SNR mask

Receiver B



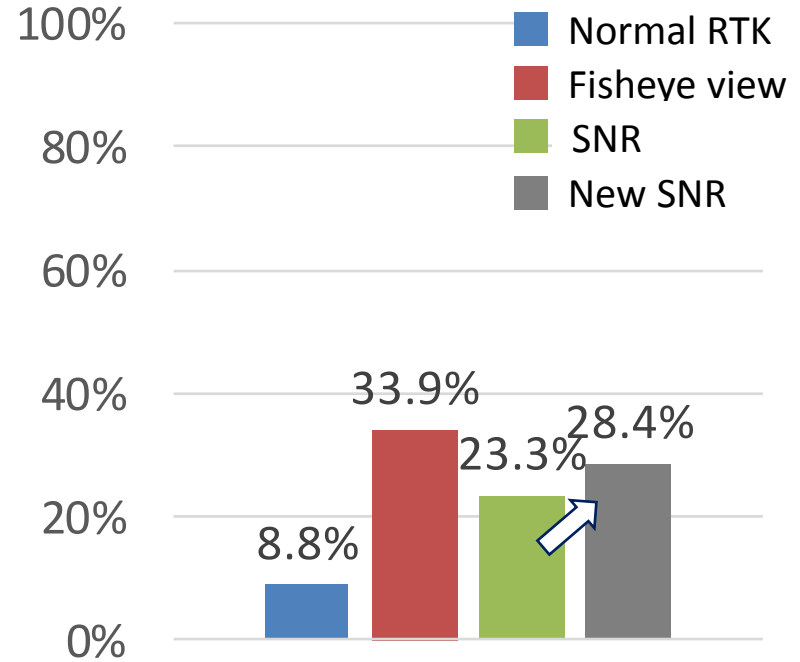
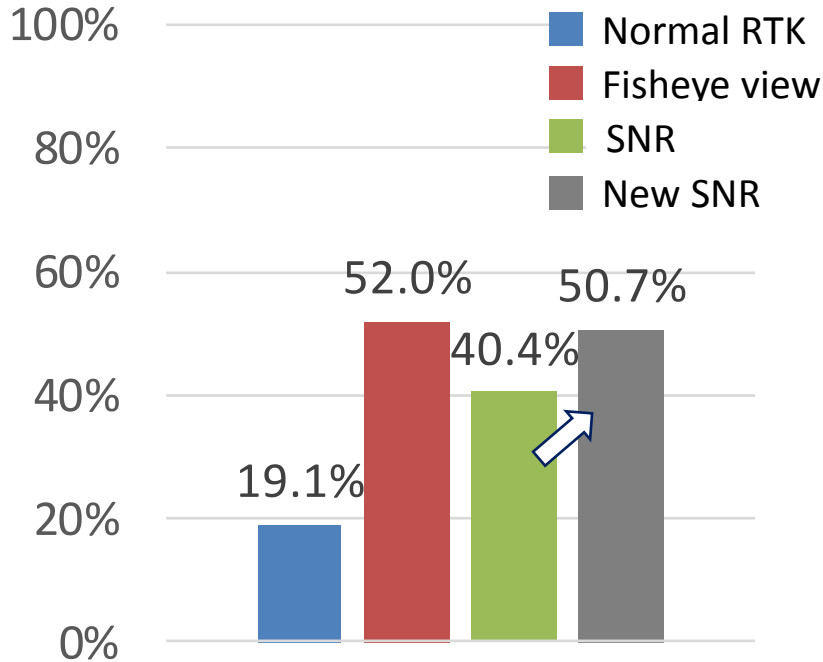
SNR mask

No Navigation Data



New SNR mask

No Navigation Data



# Conclusion

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- 3 methods were evaluated at the static positioning
  - Sky obstacles mask by precise 3D-map showed almost the same performance as a fisheye view mask
  - The SNR based mask is the powerful and effective method to remove the quality deterioration signal
  - Available results of applying conventional methods are improved more than 2 times
- Additional experiments for the strong reflected signal
  - As expected, fisheye view exclusion improved powerfully than SNR
  - New SNR mask was proposed to refer the fisheye view mask
  - The proposed SNR mask is able to be excluded strong reflected signal



Thank you for your attention!